III Year – I SEMESTER

T	P	C
3+1*	0	3

DYNAMICS OF MACHINERY

Course Objectives:

1. To equip the student with fundamental knowledge of dynamics of machines so that student can appreciate problems of dynamic force balance, transmissibility of forces, isolation of systems, vibrations.
2. Develop knowledge of analytical and graphical methods for calculating balancing of rotary and reciprocating masses.
3. Develop understanding of vibrations and its significance on engineering design.
4. Develop understanding of dynamic balancing, flywheel analysis, gyroscopic forces and moments.

UNIT – I

PRECESSION: Gyroscopes, effect of precession motion on the stability of moving vehicles such as motor car, motor cycle, aero planes and ships, static and dynamic force analysis of planar mechanisms, (Demonstration of models in video show).

UNIT – II

FRICTION: Inclined plane, friction of screw and nuts, pivot and collar, uniform pressure, uniform wear, friction circle and friction axis: lubricated surfaces, boundary friction, film lubrication.

CLUTCHES: Friction clutches- single disc or plate clutch, multiple disc clutch, cone clutch, centrifugal clutch.

BRAKES AND DYNAMOMETERS: Simple block brakes, internal expanding brake, band brake of vehicle. General description and operation of dynamometers: Prony, Rope brake, Epicyclic, Bevis Gibson and belt transmission,

UNIT – III

TURNING MOMENT DIAGRAMS: Dynamic force analysis of slider crank mechanism**,** inertia torque, angular velocity and acceleration of connecting rod, crank effort and turning moment diagrams – fluctuation of energy – fly wheels and their design.

UNIT-IV

GOVERNERS: Watt, porter and proell governors, spring loaded governors

– Hartnell and Hartung with auxiliary springs. sensitiveness, isochronism and hunting.

UNIT – V

BALANCING: Balancing of rotating masses single and multiple – single and different planes, use analytical and graphical methods. Primary, secondary, and higher balancing of reciprocating masses. analytical and graphical methods, unbalanced forces and couples – examination of "V" multi cylinder in line and radial engines for primary and secondary balancing, locomotive balancing, hammer blow, swaying couple, variation of tractive effort.

UNIT – VI

VIBRATIONS: Free Vibration of spring mass system – oscillation of pendulums, centers of oscillation and suspension. transverse loads, vibrations of beams with concentrated and distributed loads. Dunkerly's methods, Raleigh's method, whirling of shafts, critical speeds, torsional vibrations, two and three rotor systems, Simple problems on forced damped vibration, vibration isolation and transmissibility.

TEXT BOOKS :

1. Theory of Machines / S.S Ratan/ Mc. Graw Hill Publ.
2. Mechanism and machine theory by Ashok G. Ambedkar, PHI Publications.

REFERENCES :

1. Mechanism and Machine Theory / JS Rao and RV Dukkipati / New Age.
2. Theory of Machines / Shiegly / MGH
3. Theory of Machines / Thomas Bevan / CBS Publishers
4. Theory of machines / Khurmi / S.Chand.

Course outcomes:

Upon successful completion of this course the student should be able to:

1. Analyze stabilization of sea vehicles, aircrafts and automobile vehicles.
2. Compute frictional losses, torque transmission of mechanical systsms.
3. Analyze dynamic force analysis of slider crank mechanism and design of flywheel.
4. Understand how to determine the natural frequencies of continuous systems starting from the general equation of displacement.
5. Understand balancing of reciprocating and rotary masses.

III Year – I SEMESTER	T	P	C
	3+1*	0	3

METAL CUTTING & MACHINE TOOLS

Course objectives:

1. The course provides students with fundamental knowledge and principles in material removal processes.
2. In this course, the students apply the fundamentals and principles of metal cutting to practical applications through multiple labs using lathes, milling machines, grinding machines, and drill presses, Computer Numerical Control etc.
3. To demonstrate the fundamentals of machining processes and machine tools.
4. To develop knowledge and importance of metal cutting parameters.
5. To develop fundamental knowledge on tool materials, cutting fluids and tool wear mechanisms.
6. To apply knowledge of basic mathematics to calculate the machining parameters for different machining processes.

UNIT – I

FUNDAMENTALS OF MACHINING:

Elementary treatment of metal cutting theory – element of cutting process – geometry of single point tool angles, chip formation and types of chips – built up edge and its effects chip breakers, mechanics of orthogonal cutting – Merchant's force diagram, cutting forces, cutting speeds, feed, depth of cut, tool life, coolants, tool materials.

UNIT – II

LATHE MACHINES:

Engine lathe – principle of working, specification of lathe – types of lathe – work holders tool holders – box tools taper turning, thread turning – for lathes and attachments, constructional features of speed gear box and feed gear box. Turret and capstan lathes – collet chucks – other work holders – tool holding devices – box and tool layout. Principal features of automatic lathes – classification – single spindle and multi-spindle automatic lathes – tool layout and cam design for automats.

UNIT – III

SHAPING, SLOTTING AND PLANNING MACHINES: Principles of working – principal parts – specifications, operations performed, machining time calculations.

DRILLING & BORING MACHINES: Principles of working, specifications, types, operations performed – tool holding devices – twist drill – Boring Machines – fine Boring Machines – jig boring machine, deep hole Drilling Machine.

UNIT – IV

MILLING MACHINES: Principles of working – specifications – classification of Milling Machines – Principle features of horizontal, vertical and universal Milling Machine, machining operations, types of cutters, geometry of milling cutters – methods of indexing, accessories to milling machines.

UNIT –V

FINISHING PROCESSES: Theory of grinding – classification of grinding machines, cylindrical and surface grinding machines, tool and cutter grinding machines, different types of abrasives, bonds, specification and selection of a grinding wheel. Lapping, Honing & Broaching operations, comparison to grinding.

UNIT - VI

JIGS & FIXTURES: Principles of design of jigs and fixtures and uses, classification of jigs & fixtures, principles of location and clamping, types of clamping & work holding devices, typical examples of jigs and fixtures.

CNC MACHINE TOOLS: CNC Machines, working principle, classification, constructional features of CNC machines, CNC controller, types of motion controls in CNC machines, applications of CNC machines.

TEXT BOOKS:

1. Production Technology by R.K. Jain and S.C. Gupta.
2. Workshop Technology – B.S.Raghu Vamshi – Vol II

REFERENCES:

1. Metal cutting Principles by M.C. Shaw
2. Metal cutting and machine tools by Boothroyd
3. Production Technology by H.M.T. (Hindustan Machine Tools).
4. Production Engineering, K.C Jain & A.K Chitaley, PHI Publishers

5. Manufacturing technology II, P.N Rao
6. Technology of machine tools, S.F.Krar, A.R. Gill, Peter SMID, TMH (I)

Course Outcomes :

Upon successful completion of this course, the students will be able to:

1) Apply cutting mechanics to metal machining based on cutting force and power consumption.
2) Operate lathe, milling machines, drill press, grinding machines, etc.
3) Select cutting tool materials and tool geometries for different metals.
4) Select appropriate machining processes and conditions for different metals.
5) Learn machine tool structures and machining economics.
6) Write simple CNC programs and conduct CNC machining.

III Year – I SEMESTER

T	P	C
3+1*	0	3

DESIGN OF MACHINE MEMBERS – I

Course Objectives:

1. The student shall gain appreciation and understanding of the design function in mechanical engineering, the steps involved in designing and the relation of design activity with manufacturing activity
2. Selection of proper materials to different machine elements based on their physical and mechanical properties.
3. Learn and understanding of the different types of failure modes and criteria.
4. Procedure for the different machine elements such as fasteners, shafts, couplings, keys, axially loaded joints etc.

UNIT – I

INTRODUCTION: General considerations in the design of Engineering Materials and their properties – selection –Manufacturing consideration in design, tolerances and fits –BIS codes of steels.

STRESSES IN MACHINE MEMBERS: Simple stresses – combined stresses – torsional and bending stresses – impact stresses – stress strain relation – various theories of failure – factor of safety – design for strength and rigidity – preferred numbers. the concept of stiffness in tension, bending, torsion and combined situations – static strength design based on fracture toughness.

UNIT – II

STRENGTH OF MACHINE ELEMENTS: Stress concentration – theoretical stress concentration factor – fatigue stress concentration factor notch sensitivity – design for fluctuating stresses – endurance limit – estimation of endurance strength – goodman's line – soderberg's line – modified goodman's line.

UNIT – III

Riveted and welded joints – design of joints with initial stresses – eccentric loading.

Bolted joints – design of bolts with pre-stresses – design of joints under eccentric loading – locking devices – both of uniform strength, different seals.

UNIT – IV

KEYS, COTTERS AND KNUCKLE JOINTS: Design of keys-stresses in keys-cotter joints-spigot and socket, sleeve and cotter, jib and cotter joints-knuckle joints.

SHAFTS: Design of solid and hollow shafts for strength and rigidity – design of shafts for combined bending and axial loads – shaft sizes – BIS code. Use of internal and external circlips, gaskets and seals (stationary & rotary).

UNIT – V

SHAFT COUPLING: Rigid couplings – muff, split muff and flange couplings, flexible couplings – flange coupling (modified).

UNIT – VI

MECHANICAL SPRINGS:

Stresses and deflections of helical springs – extension -compression springs – springs for fatigue loading, energy storage capacity – helical torsion springs – co-axial springs, leaf springs.

TEXT BOOKS:

1. Machine Design, V.Bandari, TMH Publishers
2. Machine design – Pandya & Shah
3. Machine Design PSG Data hand book

REFERENCES:

1. Design of Machine Elements / V.M. Faires
2. Machine design / Schaum Series.
3. Data books (1) PSG College of technology (2) Mahadevan

Course outcomes:

Upon successful completion of this course student should be able to:

1. Apply the design procedure to engineering problems, including the consideration of technical and manufacturing constraints.
2. Select suitable materials and significance of tolerances and fits in critical design applications.
3. Utilize design data hand book and design the elements for strength, stiffness and fatigue.
4. Identify the loads, the machine members subjected and calculate static and dynamic stresses to ensure safe design.

III Year – I SEMESTER

T	P	C
3+1*	0	3

INSTRUMENTATION & CONTROL SYSTEMS

Course Objectives:

The course focuses on imparting the principles of measurement which includes the working mechanism of various sensors and devices, that are in use to measure the important physical variables of various mechatronic systems.

UNIT – I

Definition – Basic principles of measurement – measurement systems, generalized configuration and functional descriptions of measuring instruments – examples. dynamic performance characteristics – sources of error, classification and elimination of error.

Measurement of Displacement: Theory and construction of various transducers to measure displacement – piezo electric, inductive, capacitance, resistance, ionization and photo electric transducers, calibration procedures.

UNIT – II

MEASUREMENT OF TEMPERATURE: Classification – ranges – various principles of measurement – expansion, electrical resistance – thermistor – thermocouple – pyrometers – temperature indicators.

MEASUREMENT OF PRESSURE: Units – classification – different principles used. manometers, piston, bourdon pressure gauges, bellows – diaphragm gauges. low pressure measurement – thermal conductivity gauges – ionization pressure gauges, mcleod pressure gauge.

UNIT – III

MEASUREMENT OF LEVEL : Direct method – indirect methods – capacitative, ultrasonic, magnetic, cryogenic fuel level indicators – bubler level indicators.

FLOW MEASUREMENT: Rotameter, magnetic, ultrasonic, turbine flow meter, hot – wire anemometer, laser doppler anemometer (LDA).

MEASUREMENT OF SPEED : Mechanical tachometers – electrical tachometers – stroboscope, noncontact type of tachometer

Measurement of Acceleration and Vibration: Different simple instruments – principles of seismic instruments – vibrometer and accelerometer using this principle.

UNIT – IV

STRESS STRAIN MEASUREMENTS : Various types of stress and strain measurements – electrical strain gauge – gauge factor – method of usage of resistance strain gauge for bending compressive and tensile strains – usage for measuring torque, strain gauge rosettes.

UNIT – V

MEASUREMENT OF HUMIDITY – Moisture content of gases, sling psychrometer, absorption psychrometer, dew point meter.

MEASUREMENT OF FORCE, TORQUE AND POWER- Elastic force meters, load cells, torsion meters, dynamometers.

UNIT – VI

ELEMENTS OF CONTROL SYSTEMS : Introduction, importance – classification – open and closed systems, servomechanisms–examples with block diagrams–temperature, speed & position control systems.

TEXT BOOKS:

1. Measurement Systems: Applications & design by D.S Kumar.
2. Mechanical Measurements / BeckWith, Marangoni,Linehard, PHI / PE.

REFERENCES:

1. Measurement systems: Application and design, Doeblin Earnest. O. Adaptation by Manik and Dhanesh/ TMH.
2. Experimental Methods for Engineers / Holman.
3. Mechanical and Industrial Measurements / R.K. Jain/ Khanna Publishers.
4. Instrumentation, measurement & analysis by B.C.Nakra & K.K.Choudhary, TMH.

Course outcomes:

After undergoing the course the student can select appropriate device for the measurement of parameters like temperature, pressure, speed, stress, humidity, flow velocity etc., and justify its use through characteristics and performance.

III Year – I SEMESTER

T	P	C
3+1*	0	3

THERMAL ENGINEERING – II

(Use of steam tables and Mollier chart is allowed)

Course objectives:

This course is intended to provide basic knowledge of components being used in steam and gas power plant cycles and to analyse the energy transfers and transformations in these components including individual performance evaluation.

UNIT – I

BASIC CONCEPTS: Rankine cycle - schematic layout, thermodynamic analysis, concept of mean temperature of heat addition, methods to improve cycle performance – regeneration & reheating. combustion: fuels and combustion, concepts of heat of reaction, adiabatic flame temperature, stoichiometry, flue gas analysis.

UNIT II

BOILERS : Classification – working principles of L.P & H.P boilers with sketches – mountings and accessories – working principles, boiler horse power, equivalent evaporation, efficiency and heat balance – draught, classification – height of chimney for given draught and discharge, condition for maximum discharge, efficiency of chimney – artificial draught, induced and forced.

UNIT – III

STEAM NOZZLES: Function of a nozzle – applications - types, flow through nozzles, thermodynamic analysis – assumptions -velocity of fluid at nozzle exit-Ideal and actual expansion in a nozzle, velocity coefficient, condition for maximum discharge, critical pressure ratio, criteria to decide nozzle shape: Super saturated flow, its effects, degree of super saturation and degree of under cooling - Wilson line.

STEAM TURBINES: Classification – impulse turbine; mechanical details – velocity diagram – effect of friction – power developed, axial thrust, blade or diagram efficiency – condition for maximum efficiency. De-laval turbine - methods to reduce rotor speed-velocity compounding, pressure compounding and velocity & pressure compounding, velocity and pressure variation along the flow – combined velocity diagram for a velocity compounded impulse turbine, condition for maximum efficiency.

UNIT IV

REACTION TURBINE: Mechanical details – principle of operation, thermodynamic analysis of a stage, degree of reaction –velocity diagram – Parson's reaction turbine – condition for maximum efficiency – calculation of blade height.

STEAM CONDENSERS: Requirements of steam condensing plant – classification of condensers – working principle of different types – vacuum efficiency and condenser efficiency – air leakage, sources and its affects, air pump- cooling water requirement.

UNIT – V

GAS TURBINES: Simple gas turbine plant – ideal cycle, essential components – parameters of performance – actual cycle – regeneration, inter cooling and reheating –closed and semi-closed cycles – merits and demerits, types of combustion chambers.

UNIT – VI

JET PROPULSION : Principle of operation –classification of jet propulsive engines – working principles with schematic diagrams and representation on t-s diagram - thrust, thrust power and propulsion efficiency – turbo jet engines – needs and demands met by turbo jet – schematic diagram, thermodynamic cycle, performance evaluation, thrust augmentation – methods.

Rockets : Application – working principle – classification – propellant type – thrust, propulsive efficiency – specific impulse – solid and liquid propellant rocket engines.

TEXT BOOKS:

1. Thermodynamics and Heat Engines, Volume 2 - R.Yadav- Central book depot.
2. Gas Turbines – V.Ganesan /TMH
3. Heat Engineering – V.P Vasandani and D.S Kumar- Metropolitan Book Company, New Delhi

REFERENCES:

1. Gas Turbines and Propulsive Systems – P.Khajuria & S.P.Dubey - /Dhanpatrai
2. Gas Turbines / Cohen, Rogers and Saravana Muttoo / Addison Wesley – Longman
3. Thermal Engineering-R.S Khurmi/JS Gupta/S.Chand.

4. Thermal Engineering-P.L.Bellaney/ Khanna publishers.
5. Thermal Engineering-M.L.Marthur & Mehta/Jain bros

Course outcomes:

After undergoing this course the student is expected to understand the working of steam and gas power plant cycles and also should be able to analyze and evaluate the performance of individual components. The student also should be in a position to understand basic principles of Jet propulsion and rocket engineering.

III Year – I SEMESTER

T	P	C
3+1*	0	3

METROLOGY

Course objectives:

The students will learn

1. Inspection of engineering parts with various precision instruments.
2. Design of part, tolerances and fits.
3. Principles of measuring instruments and gauges and their uses.
4. Evaluation and inspection of surface roughness.
5. Inspection of spur gear and thread elements.
6. Machine tool testing to evaluate machine tool quality.

UNIT-I

SYSTEMS OF LIMITS AND FITS: Introduction, nominal size, tolerance, limits, deviations, fits -Unilateral and bilateral tolerance system, hole and shaft basis systems- interchangeability, determistic & statistical tolerancing, selective assembly. International standard system of tolerances, selection of limits and tolerances for correct functioning.

UNIT-II

LINEAR MEASUREMENT: Length standards, end standards, slip gauges- calibration of the slip gauges, dial indicators, micrometers.

MEASUREMENT OF ANGLES AND TAPERS:

Different methods – bevel protractor, angle slip gauges- angle dekkor- spirit levels- sine bar- sine table, rollers and spheres used to measure angles and tapers.

LIMIT GAUGES:

Taylor's principle – design of go and no go gauges; plug, ring, snap, gap, taper, profile and position gauges.

UNIT-III

OPTICAL MEASURING INSTRUMENTS: Tools maker's microscope and uses - autocollimators, optical projector, optical flats and their uses.

INTERFEROMETRY:

Interference of light, Michaleson's interferometer, NPL flatness interferometer, and NPL gauge interferometer.

UNIT-IV

SURFACE ROUGHNESS MEASUREMENT: Differences between

surface roughness and surface waviness –Numerical assessment of surface finish-CLA, Rt., R.M.S. Rz, R10 values, Method of measurement of surface finish – Profilograph, Talysurf, ISI symbols for indication of surface finish.

COMPARATORS: Types - mechanical, optical , electrical and electronic, pneumatic comparators and their uses.

UNIT – V

GEAR MEASUREMENT: Nomenclature of gear tooth, tooth thickness measurement with gear tooth vernier & flange micro meter, pitch measurement, total composite error and tooth to tooth composite errors, rolling gear tester, involute profile checking.

SCREW THREAD MEASUREMENT: Elements of measurement – errors in screw threads- concept of virtual effective diameter, measurement of effective diameter, angle of thread and thread pitch, and profile thread gauges.

UNIT – VI

FLATNESS MEASUREMENT:

Measurement of flatness of surfaces- instruments used- straight edges- surface plates – auto collimator.

MACHINE TOOL ALIGNMENT TESTS: Principles of machine tool alignment testing on lathe, drilling and milling machines.

TEXT BOOKS:

1. Engineering Metrology by R.K.Jain / Khanna Publishers
2. Engineering Metrology by Mahajan / Dhanpat Rai Publishers

REFERENCE BOOKS:

1. Dimensional Metrology, Connie Dotson, Cengage Learning.
2. Engineering Metrology by I.C.Gupta / Dhanpat Rai Publishers.
3. Precision Engineering in Manufacturing by R.L.Murthy / New Age.
4. Engineering Metrology and Measurements by NV Raghavendra, L Krishna murthy, Oxford publishers.
5. Engineering Metrology by KL Narayana, Scitech publishers.

Course outcomes:

Students will be able to design tolerances and fits for selected product quality. They can choose appropriate method and instruments for inspection of various gear elements and thread elements. They can understand the standards of length, angles, they can understand the evaluation of surface finish and measure the parts with various comparators. The quality of the machine tool with alignment test can also be evaluated by them.

III Year – I SEMESTER

T	P	C
0	3	2

METROLOGY & INSTRUMENTATION LAB

Course Objectives:

The Metrology and instrumentation Laboratory course is designed for measuring and gauging instruments for inspection of precision linear, geometric forms, angular and surface finish measurements. The student can learn the measurements with and calibration of instruments. They also understand the machine tool alignment test. Instrumentation lab introduces the students with the theory and methods for conducting experimental work in the laboratory and calibration of various instruments for measuring pressure, temperature, displacement, speed, vibration etc.

Note: The students have to conduct at least 8 experiments from each lab.

METROLOGY LAB

1. Measurement of lengths, heights, diameters by vernier calipers, micrometers etc.
2. Measurement of bores by internal micrometers and dial bore indicators.
3. Use of gear tooth vernier caliper for tooth thickness inspection and flange micro meter for checking the chordal thickness of spur gear.
4. Machine tool alignment test on the lathe.
5. Machine tool alignment test on drilling machine.
6. Machine tool alignment test on milling machine.
7. Angle and taper measurements with bevel protractor, Sine bars, rollers and balls.
8. Use of spirit level in finding the straightness of a bed and flatness of a surface.
9. Thread inspection with two wire/ three wire method & tool makers microscope.
10. Surface roughness measurement with roughness measuring instrument.

INSTRUMENTATION LAB

1. Calibration of pressure gauge.
2. Calibration of transducer for temperature measurement.
3. Study and calibration of LVDT transducer for displacement measurement.

4. Calibration of strain gauge.
5. Calibration of thermocouple.
6. Calibration of capacitive transducer.
7. Study and calibration of photo and magnetic speed pickups.
8. Calibration of resistance temperature detector.
9. Study and calibration of a rotameter.
10. Study and use of a seismic pickup for the measurement of vibration amplitude of an engine bed at various loads.
11. Study and calibration of Mcleod gauge for low pressure.

Course outcomes:

Metrology Lab

Student will become familiar with the different instruments that are available for linear, angular, roundness and roughness measurements they will be able to select and use the appropriate measuring instrument according to a specific requirement (in terms of accuracy, etc).

Instrumentation Lab:

Students will be able to select proper measuring instrument and know requirement of calibration, errors in measurement etc. They can perform accurate measurements.

III Year – I SEMESTER

T	P	C
0	3	2

MACHINE TOOLS LAB

Course objectives:

The students are required to understand the parts of various machine tools and operate them. They are required to understand the different shapes of products that can be produced on these machine tools.

1. Introduction of general purpose machines -lathe, drilling machine, milling machine, shaper, planing machine, slotting machine, cylindrical grinder, surface grinder and tool and cutter grinder.
2. Step turning and taper turning on lathe machine
3. Thread cutting and knurling on -lathe machine.
4. Drilling and tapping
5. Shaping and planning
6. Slotting
7. Milling
8. Cylindrical surface grinding
9. Grinding of tool angles.

Course outcomes:

The students can operate different machine tools with understanding of work holders and operating principles to produce different part features to the desired quality.

III Year – I SEMESTER

T	P	C
0	3	2

INTELLECTUAL PROPERTY RIGHTS AND PATENTS

Unit I

Introduction to Intellectual Property Law – Evolutionary past – Intellectual Property Law Basics - Types of Intellectual Property - Innovations and Inventions of Trade related Intellectual Property Rights – Agencies Responsible for Intellectual Property Registration – Infringement - Regulatory – Over use or Misuse of Intellectual Property Rights - Compliance and Liability Issues.

Unit II

Introduction to Copyrights – Principles of Copyright – Subject Matters of Copyright – Rights Afforded by Copyright Law –Copyright Ownership – Transfer and Duration – Right to Prepare Derivative Works –Rights of Distribution – Rights of performers **–** Copyright Formalities and Registration – Limitations – Infringement of Copyright – International Copyright Law- Semiconductor Chip Protection Act.

Unit III

Introduction to Patent Law – Rights and Limitations – Rights under Patent Law – Patent Requirements – Ownership and Transfer – Patent Application Process and Granting of Patent – Patent Infringement and Litigation – International Patent Law – Double Patenting – Patent Searching – Patent Cooperation Treaty – New developments in Patent Law- Invention Developers and Promoters.

Unit IV

Introduction to Trade Mark – Trade Mark Registration Process – Post registration procedures – Trade Mark maintenance – Transfer of rights – Inter parties Proceedings – Infringement – Dilution of Ownership of Trade Mark – Likelihood of confusion – Trade Mark claims – Trade Marks Litigation – International Trade Mark Law.

Unit V

Introduction to Trade Secrets – Maintaining Trade Secret – Physical Security – Employee Access Limitation – Employee Confidentiality Agreement – Trade Secret Law – Unfair Competition – Trade Secret Litigation – Breach of Contract – Applying State Law.

Unit VI

Introduction to Cyber Law – Information Technology Act - Cyber Crime and E-commerce – Data Security – Confidentiality – Privacy - International aspects of Computer and Online Crime.

REFERENCE BOOKS:

1. Deborah E.Bouchoux: “Intellectual Property”. Cengage learning , New Delhi.
2. Kompal Bansal & Parishit Bansal "Fundamentals of IPR for Engineers", BS Publications (Press).
3. Cyber Law. Texts & Cases, South-Western’s Special Topics Collections.
4. Prabhuddha Ganguli: ‘ Intellectual Property Rights” Tata Mc-Graw – Hill, New Delhi.
5. Richard Stim: "Intellectual Property", Cengage Learning, New Delhi.
6. R. Radha Krishnan, S. Balasubramanian: "Intellectual Property Rights", Excel Books. New Delhi.
7. M.Ashok Kumar and Mohd.Iqbal Ali: “Intellectual Property Right” Serials Pub.

III Year – II SEMESTER

T	P	C
3+1*	0	3

OPERATIONS RESEARCH

Course Objectives:

To learn the importance of Operations Research in the design, planning, scheduling, manufacturing and business applications and to use the various techniques of Operations Research in solving such problems.

UNIT – I

Development – definition– characteristics and phases – types of operation research models – applications.

ALLOCATION: Linear programming problem formulation – graphical solution – simplex method – artificial variables techniques -two–phase method, big-M method – duality principle.

UNIT – II

TRANSPORTATION PROBLEM: Formulation – optimal solution, unbalanced transportation problem – degeneracy, assignment problem – formulation – optimal solution - variants of assignment problem- traveling salesman problem.

SEQUENCING – Introduction – flow –shop sequencing – *n* jobs through two machines – *n* jobs through three machines – job shop sequencing – two jobs through 'm' machines.

UNIT – III

REPLACEMENT: Introduction – replacement of items that deteriorate with time – when money value is not counted and counted – replacement of items that fail completely, group replacement.

UNIT – IV

THEORY OF GAMES: Introduction – mini. max (max. mini) – criterion and optimal strategy – solution of games with saddle points – rectangular games without saddle points – 2 x 2 games – dominance principle – m x 2 & 2 x n games -graphical method.

WAITING LINES: Introduction – single channel – poison arrivals – exponential service times – with infinite population and finite population models– multichannel – poison arrivals – exponential service times with infinite population single channel poison arrivals.

UNIT – V

INVENTORY : Introduction – single item – deterministic models – purchase inventory models with one price break and multiple price breaks – shortages are not allowed – stochastic models – demand may be discrete variable or continuous variable – instantaneous production. Instantaneous demand and continuous demand and no set up cost. ABC & VED Analysis.

UNIT – VI

DYNAMIC PROGRAMMING: Introduction – Bellman's principle of optimality – applications of dynamic programming- capital budgeting problem – shortest path problem – linear programming problem.

SIMULATION: Definition – types of simulation models – phases of simulation– applications of simulation – inventory and queuing problems – advantages and disadvantages – simulation languages.

TEXT BOOKS:

1. Operations Research / S.D.Sharma-Kedarnath

REFERENCES:

1. Introduction to O.R/Hiller & Libermann (TMH).
2. Operations Research / A.M.Natarajan, P. Balasubramani, A. Tamilarasi / Pearson Education.
3. Operations Research: Methods & Problems / Maurice Saseini, Arhur Yaspan & Lawrence Friedman.
4. Operations Research / R.Pannerselvam,PHI Publications.
5. Operations Research / Wagner/ PHI Publications.
6. Operation Research /J.K.Sharma/MacMilan.
7. Operations Research/ Pai/ Oxford Publications
8. Operations Research/S Kalavathy / Vikas Publishers
9. Operations Research / DS Cheema/University Science Press
10. Operations Research / Ravindran, Philips, Solberg / Wiley publishers.

Course Outcomes:

After completion of the course, the student will be able to:

To solve the LP and DP problems.

To solve the Transportation, assignment, game, inventory, replacement, sequencing, queuing problems.

III Year – II SEMESTER

T	P	C
3+1*	0	3

INTERACTIVE COMPUTER GRAPHICS

Course objectives:

This course allows the students to:

1. Understand the fundamental concepts and theory of computer graphics.
2. Understand modeling, and interactive control of 3D computer graphics applications.
3. The underlying parametric surface concepts be understood.
4. Learn multimedia authoring tools.

UNIT-I

INTRODUCTION: Application areas of computer graphics, overview of graphic system, video-display devices, raster-scan systems, random scan systems, graphics monitors and work stations and input devices.

UNIT-II

OUTPUT PRIMITIVES: Points and lines, line drawing algorithms, mid-point circle algorithm,

Filled area primitives: scan-line polygon fill algorithm, boundary-fill and flood-fill algorithm.

2-D GEOMETRICAL TRANSFORMATIONS: Translation, scaling, rotation, reflection and shear transformation matrix representations and homogeneous co-ordinates, composite transformations, transformations between coordinates.

UNIT -III

2-D VIEWING : The viewing pipe-line, viewing coordinat4 reference frame, window to view-port co-ordinate transformations, viewing function, Cohen-Sutherland and Cyrus-beck line clipping algorithms, Sutherland-Hodgeman polygon clipping algorithm.

UNIT -IV

3-D OBJECT REPRESENTATION: spline representation, Hermite curve, Bezier curve and B-spline curve, Polygon surfaces, quadric surfaces, , Solid modeling Schalars – wire frame, CSG, B-rep. Bezier and B-spline surfaces, Basic illumination models, shading algorithms.

UNIT -V

3-D GEOMETRIC TRANSFORMATIONS: Translation, rotation, scaling, reflection and shear transformation and composite transformations. Visible surface detection methods: Classification, back-face detection, depth-buffer, scan-line, depth sorting.

UNIT-VI

COMPUTER ANIMATION: Design of animation sequence, general computer animation functions, raster animation, computer animation language, key frame system, motion specification.

TEXT BOOKS:

1. " Computer Graphics C version" Donald Hearn and M. Pauline Baker, Pearson/PHI
2. "Computer Graphics Principles & practice", second edition in C, Foley, VanDam, Feiner and Hughes, Pearson Education.

REFERENCES:

1. "Computer Graphics Second edition", Zhigand xiang, Roy Plastock, Schaum's outlines, Tata Mc-Graw hill edition.
2. Procedural elements for Computer Graphics, David F Rogers, Tata Mc Graw hill, 2nd edition.
3. "Principles of Interactive Computer Graphics", Neuman and Sproul, TMH.
4. Computer Graphics, Steven Harrington, TMH.

Course outcomes:

Upon successful completion of the course, students will be able to:

1. Use the principles and commonly used paradigms and techniques of computer graphics.
2. Write basic graphics application programs including animation.
3. Design programs to display graphic images to given specifications.
4. Possess in-depth knowledge of display systems, image synthesis, shape modeling, and interactive control of 3D computer graphics applications.

III Year – II SEMESTER

T	P	C
3+1*	0	3

DESIGN OF MACHINE MEMBERS– II

Course Objectives:

- This course gives the insight of slider and roller bearings and the life prediction.
- Learn to design I.C engine parts.
- Design the mechanical systems for power transmission elements such as gears,belts,ropes,chains, keys and levers.

UNIT – I

BEARINGS: Classification of bearings- applications, types of journal bearings – lubrication – bearing modulus – full and partial bearings – clearance ratio – heat dissipation of bearings, bearing materials – journal bearing design – ball and roller bearings – static loading of ball & roller bearings, bearing life.

UNIT – II

ENGINE PARTS: Connecting Rod: Thrust in connecting rod – stress due to whipping action on connecting rod ends – cranks and crank shafts, strength and proportions of over hung and center cranks – crank pins, crank shafts.

UNIT –III

Pistons, forces acting on piston – construction design and proportions of piston, cylinder, cylinder liners.

UNIT – IV

Design of curved beams: introduction, stresses in curved beams, expression for radius of neutral axis for rectangular, circular, trapezoidal and t-section, design of crane hooks, c –clamps**.**

UNIT – V

POWER TRANSMISSIONS SYSTEMS, PULLEYS: Transmission of power by belt and rope drives , transmission efficiencies, belts – flat and v types – ropes - pulleys for belt and rope drives, materials, chain drives

DESIGN OF POWER SCREWS: Design of screw, square ACME, buttress screws, design of nut, compound screw, differential screw, ball screw-possible failures.

UNIT – VI

SPUR & HELICAL GEAR DRIVES: Spur gears- helical gears – load concentration factor – dynamic load factor, surface compressive strength – bending strength – design analysis of spur gears – estimation of centre distance, module and face width, check for plastic deformation, check for dynamic and wear considerations.

MACHINE TOOL ELEMENTS: Levers and brackets: design of levers – hand levers-foot lever – cranked lever – lever of a lever loaded safety valve-rocker arm straight – angular- design of a crank pin – brackets- hangers- wall boxes.

TEXT BOOKS:

1. Machine Design, V.Bandari, TMH Publishers
2. Machine Design PSG Data hand book
3. Machine Design, Pandya & Shaw, Charotar publishers

REFERENCES:

1. Machine Design / R.N. Norton
2. Data Books : (I) P.S.G. College of Technology (ii) Mahadevan
3. Mech. Engg. Design / JE Shigley

Course outcomes:

At the end of the course

1. The student will able to select the suitable bearing based on the application of the loads and predict the life of the bearing.
2. Design power transmission elements such as gears, belts, chains, pulleys, ropes, levers and power screws.
3. Design of IC Engines parts.

III Year – II SEMESTER

T	P	C
3+1*	0	3

ROBOTICS

Course Objectives:

1. To give students practice in applying their knowledge of mathematics, science, and Engineering and to expand this knowledge into the vast area of robotics.
2. The students will be exposed to the concepts of robot kinematics, Dynamics, Trajectory planning.
3. Mathematical approach to explain how the robotic arm motion can be described.
4. The students will understand the functioning of sensors and actuators.

UNIT-I

INTRODUCTION: Automation and Robotics, CAD/CAM and Robotics – An over view of Robotics – present and future applications – classification by coordinate system and control system.

UNIT – II

COMPONENTS OF THE INDUSTRIAL ROBOTICS: Function line diagram representation of robot arms, common types of arms. Components, Architecture, number of degrees of freedom – Requirements and challenges of end effectors, determination of the end effectors, comparison of Electric, Hydraulic and Pneumatic types of locomotion devices.

UNIT – III

MOTION ANALYSIS: Homogeneous transformations as applicable to rotation and translation – problems.

MANIPULATOR KINEMATICS: Specifications of matrices, D-H notation joint coordinates and world coordinates Forward and inverse kinematics – problems.

UNIT – IV

Differential transformation and manipulators, Jacobians – problems

Dynamics: Lagrange – Euler and Newton – Euler formulations – Problems.

UNIT V

General considerations in path description and generation. Trajectory planning and avoidance of obstacles, path planning, Skew motion, joint

integrated motion –straight line motion – Robot programming, languages and software packages-description of paths with a robot programming language..

UNIT VI

ROBOT ACTUATORS AND FEED BACK COMPONENTS:

Actuators: Pneumatic, Hydraulic actuators, electric & stepper motors.

Feedback components: position sensors – potentiometers, resolvers, encoders – Velocity sensors.

ROBOT APPLICATIONS IN MANUFACTURING: Material Transfer - Material handling, loading and unloading- Processing - spot and continuous arc welding & spray painting - Assembly and Inspection.

TEXT BOOKS:

1. Industrial Robotics / Groover M P /Pearson Edu.
2. Robotics and Control / Mittal R K & Nagrath I J / TMH.

REFERENCES:

1. Robotics / Fu K S/ McGraw Hill.
2. Robotic Engineering / Richard D. Klafter, Prentice Hall.
3. Robot Analysis and Intelligence / Asada and Slow time / Wiley Inter-Science.
4. Introduction to Robotics / John J Craig / Pearson Edu.

Course outcomes:

Upon successful completion of this course you should be able to:

1. Identify various robot configuration and components.
2. Select appropriate actuators and sensors for a robot based on specific application.
3. Carry out kinematic and dynamic analysis for simple serial kinematic chains.
4. Perform trajectory planning for a manipulator by avoiding obstacles.

III Year – II SEMESTER

T	P	C
3+1*	0	3

HEAT TRANSFER

(Heat transfer data book allowed)

Course Objectives:

This course is intended to impart knowledge of principles of heat transfer and analyze the heat exchange process in various modes for the evaluation of rate of heat transfer and the temperature distribution in different configurations.

UNIT – I

INTRODUCTION: Modes and mechanisms of heat transfer – basic laws of heat transfer –General discussion about applications of heat transfer.

CONDUCTION HEAT TRANSFER: Fourier rate equation – general heat conduction equation in cartesian, cylindrical and Spherical coordinates. Steady, unsteady and periodic heat transfer – initial and boundary conditions.

ONE DIMENSIONAL STEADY STATE CONDUCTION HEAT TRANSFER: Homogeneous slabs, hollow cylinders and spheres – overall heat transfer coefficient – electrical analogy – critical radius of insulation- Variable thermal conductivity – systems with heat sources or heat generation.

UNIT – II

extended surface (fins) heat Transfer – long fin, fin with insulated tip and short fin, application to error measurement of temperature.

ONE DIMENSIONAL TRANSIENT CONDUCTION HEAT TRANSFER: Systems with negligible internal resistance – significance of biot and fourier numbers - chart solutions of transient conduction systems.

UNIT – III

CONVECTIVE HEAT TRANSFER: Classification of convective heat transfer – dimensional analysis as a tool for experimental investigation – Buckingham Pi Theorem for forced and free convection, application for developing semi – empirical non- dimensional correlation for convective heat transfer – Significance of non-dimensional numbers – concepts of continuity, momentum and Energy Equations.

UNIT –IV

FORCED CONVECTION

EXTERNAL FLOWS: Concepts about hydrodynamic and thermal

boundary layer and use of empirical correlations for convective heat transfer -flat plates and cylinders.

INTERNAL FLOWS: Concepts about hydrodynamic and thermal entry lengths – division of internal flow based on this –use of empirical relations for horizontal pipe flow and annulus flow.

FREE CONVECTION: Development of hydrodynamic and thermal boundary layer along a vertical plate – use of empirical relations for vertical plates and pipes.

UNIT V

HEAT TRANSFER WITH PHASE CHANGE

BOILING: Pool boiling – regimes- calculations on nucleate boiling, critical heat flux and film boiling.

CONDENSATION: Film wise and drop wise condensation –nusselt's theory of condensation on a vertical plate - film condensation on vertical and horizontal cylinders using empirical correlations.

HEAT EXCHANGERS:

Classification of heat exchangers – overall heat transfer coefficient and fouling factor – concepts of LMTD and NTU methods – Problems.

UNIT VI

RADIATION HEAT TRANSFER:

Emission characteristics and laws of black-body radiation – Irradiation – total and monochromatic quantities – laws of Planck, Wien, Kirchoff, Lambert, Stefan and Boltzmann– heat exchange between two black bodies – concepts of shape factor – Emissivity – heat exchange between grey bodies – radiation shields – electrical analogy for radiation networks.

TEXT BOOKS:

1. Heat Transfer - HOLMAN/TMH
2. Heat Transfer – P.K.Nag/ TMH
3. Principles of Heat Transfer – Frank Kreith, RM Manglik & MS Bohn, Cengage learning publishers.

REFERENCE BOOKS:

1. Heat and Mass Transfer – Arora and Domkundwar, Dhanpatrai & sons.
2. Fundamentals of Engg. Heat and Mass Transfer / R.C.SACHDEVA / New Age International.
3. Heat and Mass Transfer –Cengel- McGraw Hill.

4. Heat and Mass Transfer – D.S.Kumar / S.K.Kataria & Sons.

Course outcomes:

The student after undergoing this course is expected to know the principles of heat transfer and be able to apply to practical situations where in heat exchange takes place through various modes of heat transfer including phase change.

III Year – II SEMESTER

T	P	C
3+1*	0	3

INDUSTRIAL ENGINEERING & MANAGEMENT

Course Objectives:

1. To impart fundamental knowledge and skill sets required in the Industrial Management and Engineering profession, which include the ability to apply basic knowledge of mathematics, probability and statistics, and the domain knowledge of Industrial Management and Engineering.
2. To produce graduates with the ability to adopt a system approach to design, develop, implement and innovate integrated systems that include people, materials, information, equipment and energy.
3. To enable students to understand the interactions between engineering, business, technological and environmental spheres in the modern society.
4. To enable students to understand their role as engineers and their impact to society at the national and global context.

Unit – I

INTRODUCTION: Definition of industrial engineering (I.E), development, applications, role of an industrial engineer, differences between production management and industrial engineering, quantitative tools of IE and productivity measurement. concepts of management, importance, functions of management, scientific management, Taylor's principles, theory X and theory Y, Fayol's principles of management.

Unit – II

PLANT LAYOUT: Factors governing plant location, types of production layouts, advantages and disadvantages of process layout and product layout, applications, quantitative techniques for optimal design of layouts, plant maintenance, preventive and breakdown maintenance.

Unit – III

OPERATIONS MANAGEMENT: Importance, types of production, applications, workstudy, method study and time study, work sampling, PMTS, micro-motion study, rating techniques, MTM, work factor system, principles of Ergonomics, flow process charts, string diagrams and Therbligs.

Unit – IV

STATISTICAL QUALITY CONTROL: Quality control, its importance, SQC, attribute sampling inspection with single and double sampling, Control charts – $\overline{X}$ and R – charts $\overline{X}$ AND *S* charts and their applications, numerical examples.

TOTAL QUALITY MANAGEMENT: zero defect concept, quality circles, implementation, applications, ISO quality systems. six sigma – definition, basic concepts

Unit – V

RESOURCE MANAGEMENT: Concept of human resource management, personnel management and industrial relations, functions of personnel management, Job-evaluation, its importance and types, merit rating, quantitative methods, wage incentive plans, types.

Unit - VI

VALUE ANALYSIS: Value engineering, implementation procedure, enterprise resource planning and supply chain management.

PROJECT MANAGEMENT: PERT, CPM – differences & applications, critical path, determination of floats, importance, project crashing, smoothing and numerical examples.

TEXT BOOKS:

1. Industrial Engineering and management by O.P Khanna, Khanna Publishers.
2. Industrial Engineering and Production Management, Martand Telsang, S.Chand & Company Ltd. New Delhi.

Reference Books:

1. Industrial Management by Bhattacharya DK, Vikas publishers.
2. Operations Management by J.G Monks, McGrawHill Publishers.
3. Industrial Engineering by Banga & Sharma.
4. Principles of Management by Koontz O' Donnel, McGraw Hill Publishers.
5. Statistical Quality Control by Gupta.
6. Industrial Engineering and Management by Raju, Cengage Publishers.

Course outcome:

Upon successful completion of this course you should be able to:

1. Design and conduct experiments, analyse, interpret data and synthesise valid conclusions.
2. Design a system, component, or process, and synthesise solutions to achieve desired needs.
3. Use the techniques, skills, and modern engineering tools necessary for engineering practice with appropriate considerations for public health and safety, cultural, societal, and environmental constraints.
4. Function effectively within multi-disciplinary teams and understand the fundamental precepts of effective project management.

III Year – II SEMESTER

T	P	C
3+1*	0	3

DEPARTMENTAL ELECTIVE – I

REFRIGERATION & AIR CONDITIONING
(Refrigeration and Psychrometric tables and charts allowed)

Course objectives:

The course is to understand the basic cycles of various refrigerating systems, their performance evaluation along with details of system components and refrigerant properties. The course is also aimed at imparting knowledge of psychrometric properties, processes which are used in airconditioning systems for comfort and industrial applications.

UNIT – I

INTRODUCTION TO REFRIGERATION: Necessity and applications – unit of refrigeration and C.O.P. – Mechanical refrigeration – types of ideal cycles of refrigeration. air refrigeration: bell coleman cycle - open and dense air systems – refrigeration systems used in air crafts and problems.

UNIT – II

VAPOUR COMPRESSION REFRIGERATION: Working principle and essential components of the plant – simple vapour compression refrigeration cycle – COP – representation of cycle on T-S and p-h charts – effect of sub cooling and super heating – cycle analysis – actual cycle influence of various parameters on system performance – use of p-h charts – numerical problems.

UNIT III

REFRIGERANTS – Desirable properties – classification - refrigerants used – nomenclature – ozone depletion – global warming.

VCR SYSTEM COMPONENTS: Compressors – general classification – comparison – advantages and disadvantages. condensers – classification – working principles evaporators – classification – working principles expansion devices – types – working principles.

UNIT IV

VAPOR ABSORPTION SYSTEM: Calculation of maximum COP – description and working of NH_3 – water system and Li Br –water (Two shell & Four shell) System, principle of operation three fluid absorption system, salient features.

STEAM JET REFRIGERATION SYSTEM: Working Principle and basic components. principle and operation of (i) thermoelectric refrigerator (ii) vortex tube.

UNIT – V

INTRODUCTION TO AIR CONDITIONING: Psychometric properties & processes – characterization of sensible and latent heat loads — need for ventilation, consideration of infiltration – load concepts of RSHF, GSHF-problems, concept of ESHF and ADP temperature.

Requirements of human comfort and concept of effective temperature-comfort chart –comfort air conditioning – requirements of industrial air conditioning, air conditioning load calculations.

UNIT – VI

AIR CONDITIONING SYSTEMS: Classification of equipment, cooling, heating humidification and dehumidification, filters, grills and registers, fans and blowers. heat pump – heat sources – different heat pump circuits.

TEXT BOOKS:

1. A Course in Refrigeration and Air conditioning / SC Arora & Domkundwar / Dhanpatrai.
2. Refrigeration and Air Conditioning / CP Arora / TMH.

REFERENCES:

1. Refrigeration and Air Conditioning / Manohar Prasad / New Age.
2. Principles of Refrigeration - Dossat / Pearson Education.
3. Basic Refrigeration and Air-Conditioning – Ananthanarayanan / TMH

Course outcomes: At the end of the course the students should be able to:
After undergoing the course the student should be in a position to analyze various refrigerating cycles and evaluate their performance. The student also should be able to perform cooling load calculations and select the appropriate process and equipment for the required comfort and industrial airconditioning.

COMPUTATIONAL FLUID DYNAMICS
(DEPARTMENTAL ELECTIVE – I)

Course Objectives:

The course aims at providing required numerical and software techniques for solving various engineering problems involving fluid flow.

UNIT-I

ELEMENTARY DETAILS IN NUMERICAL TECHNIQUES: Number system and errors, representation of integers, fractions, floating point arithmetic, loss of significance and error propagation, condition and instability, computational methods for error estimation, convergence of sequences.

UNIT – II

APPLIED NUMERICAL METHODS: Solution of a system of simultaneous linear algebraic equations, iterative schemes of matrix inversion, direct methods for matrix inversion, direct methods for banded matrices.

REVIEW OF EQUATIONS GOVERNING FLUID FLOW AND HEAT TRANSFER: Introduction, conservation of mass, Newton's second law of motion, expanded forms of navier-stokes equations, conservation of energy principle, special forms of the navier-stokes equations.

UNIT - III

Steady flow, dimensionless form of momentum and energy equations, stokes equation, conservative body force fields, stream function - vorticity formulation.

Finite difference applications in heat conduction and convention – heat conduction, steady heat conduction in a rectangular geometry, transient heat conduction, finite difference application in convective heat transfer, closure.

UNIT - IV

Finite differences, discretization, consistency, stability, and fundamentals of fluid flow modeling: introduction, elementary finite difference quotients, implementation aspects of finite-difference equations, consistency, explicit and implicit methods.

UNIT - V

Introduction to first order wave equation, stability of hyperbolic and elliptic equations, fundamentals of fluid flow modeling, conservative property, the upwind scheme.

UNIT -VI

FINITE VOLUME METHOD: Approximation of surface integrals, volume integrals, interpolation and differentiation practices, upwind interpolation, linear interpolation and quadratic interpolation.

TEXT BOOKS:

1. Numerical heat transfer and fluid flow / Suhas V. Patankar- Butter-worth Publishers.
2. Computational fluid dynamics - Basics with applications - John. D. Anderson / Mc Graw Hill.

REFERENCES:

1. Computational Fluid Flow and Heat Transfer/ Niyogi, Pearson Publications.
2. Fundamentals of Computational Fluid Dynamics – Tapan K. Sengupta / Universities Press.
3. Computational fluid dynamics, 3rd edition/Wendt/Springer publishers

Course Outcomes:

After undergoing the course the student shall be able to apply various numerical tools like finite volume, finite difference etc for solving the different fluid flow problems.

CONDITION MONITORING
(DEPARTMENTAL ELECTIVE – I)

Course Objectives:

- This course is designed to introduce the benefits and opportunities of health Monitoring and covers a range of techniques.
- The students will be exposed to a range of techniques from Vibration based methods, Thermography, Oil conditions, Debris and ultrasonic monitoring.
- Using overall vibration, vibration limit zones, broadband vibration bandwidth, alert levels, typical severity guidelines, recording overall vibration, using overall vibration for fault finding, trending overall vibration.

Identifying Resonance, Hammer Test, Self Excitation, Exciter Testing. Reducing Resonance - Effects of Frequency, Stiffness, Mass, Damping, Isolation.

UNIT-I

BASICS OF VIBRATION: Basic motion: amplitudes, period, frequency, basic parameters: displacement, velocity, acceleration, units (including dB scales) and conversions, Mass, spring and damper concept, Introduction to SDOF and MDOF systems, Natural frequencies and resonance, Forced response.

UNIT-II

VIBRATION MEASUREMENTS AND ANALYSIS: Transducers and mounting methods, data acquisition using instrumentation recorders/data loggers, time domain signal analysis, orbit analysis, Filters, Frequency domain analysis (Narrow band FFT analysis), Nyquist criteria, Sampling, aliasing, windowing and averaging.

VIBRATION MEASUREMENT AND ANALYSIS: Use of phase; bode, polar and water fall plots, constant percentage band width analysis (1/3 and 1/1 Octave analysis), envelope detection /spike energy analysis, cepstral analysis, advances in analysis (PC based and portable instruments for vibration analysis).

UNIT-III

Fault Diagnosis, Interpreting vibration measurements for common machine faults, imbalance, misalignment, mechanical looseness, bearing and gearing faults, faults in induction motors, resonances, some case studies, static and

dynamic balancing, international standards for vibration condition monitoring.

UNIT-IV

THERMOGRAPHY: The basics of infrared thermography, differences in equipment and specific wave length limitations, application of ir to: electrical inspection, mechanical inspection, energy conservation, how to take good thermal images, hands-on demonstrations focusing on proper camera settings and image interpretation, analysis of thermal images and report generation, study of thermo graphy applications

UNIT-V

OIL AND WEAR DEBRIS ANALYSIS: Basics of oil analysis, monitoring condition of oil, lubricant analysis, physio – chemical properties, moisture, tan tbn, wear debris analysis, particle counting, spectroscopy, uses & limitations, ferrography wear particle analysis, concept of ferrography, principle particle classification, size, shape, composition, concentration, analysis procedure, sampling & analytical ferrography equipments, severity rating.

UNIT-VI

ULTRASONIC MONITORING AND ANALYSIS: Ultrasonic monitoring (leak, crack and thickness) basics of ultrasonic monitoring , ultrasonic theory, test taking philosophy, ultrasonic theory, mathematics of ultrasound, equipment and transducers, inspection parameters and calibration, immersion theory, equipment quality control, flaw origins and inspection methods, UT Procedure familiarization, and study recommendations, application of ultrasound to: air leaks, steam trap testing, bearing lubrication, electrical inspection, case studies.

TEXT BOOKS:

1. The Vibration Analysis Handbook, J I Taylor (1994)
2. Machinery Vibration Condition Monitoring, Lynn, Butterworth(1989)

REFERENCE BOOKS:

1. Machinery Vibration: Measurement and Analysis. Victor Wowk (1991).
2. Mechanical fault diagnosis and condition monitoring, RA Collacott (1977).
3. The Vibration Monitoring Handbook (Coxmoor's Machine & Systems Condition Monitoring) (1998).

Course outcomes:

- Gaining invaluable insights into the benefits of Condition Monitoring.
- Understanding the reasons for selecting particular maintenance strategies.
- Understanding effective methodologies for implementing Condition Monitoring Techniques.
- Identifying the optimum maintenance strategy for different types of equipment.
- Gaining practical approaches to minimise the risk of plant and machinery breakdowns.
- Awareness of International Standards covering asset manageme.

RAPID PROTOTYPING
(DEPARTMENTAL ELECTIVE – I)

Course Objectives:

The course aims at the importance of Rapid Prototyping, classifications, models, specifications of various Rapid Prototype Techniques. To learn the different tools, soft-wares required and the applications of Rapid Prototyping.

UNIT – I

INTRODUCTION: Prototyping fundamentals, historical development, fundamentals of rapid prototyping, advantages and limitations of rapid prototyping, commonly used terms, classification of RP process.

LIQUID-BASED RAPID PROTOTYPING SYSTEMS: Stereo lithography Apparatus (SLA): models and specifications, process, working principle, photopolymers, photo polymerization, layering technology, laser and laser scanning, applications, advantages and disadvantages, case studies. Solid Ground Curing (SGC): models and specifications, process, working principle, applications, advantages and disadvantages, case studies.

UNIT-II

SOLID-BASED RAPID PROTOTYPING SYSTEMS: Laminated object manufacturing (LOM) - models and specifications, process, working principle, applications, advantages and disadvantages, case studies. Fused deposition modeling (FDM) - models and specifications, process, working principle, applications, advantages and disadvantages, case studies.

UNIT – III

POWDER BASED RAPID PROTOTYPING SYSTEMS: Selective laser sintering (SLS): models and specifications, process, working principle, applications, advantages and disadvantages, case studies. three dimensional printing (3DP): models and specifications, process, working principle, applications, advantages and disadvantages, case studies.

UNIT-IV

RAPID TOOLING: Introduction to rapid tooling (RT), conventional tooling Vs RT, Need for RT. rapid tooling classification: indirect rapid tooling methods: spray metal deposition, RTV epoxy tools, Ceramic tools, investment casting, spin casting, die casting, sand casting, 3D Keltool process. Direct rapid tooling: direct AIM, LOM Tools, DTM Rapid Tool Process, EOS Direct Tool Process and Direct Metal Tooling using 3DP.

UNIT – V

RAPID PROTOTYPING DATA FORMATS: STL Format, STL File Problems, consequence of building valid and invalid tessellated models, STL file Repairs: Generic Solution, other Translators, Newly Proposed Formats.

RAPID PROTOTYPING SOFTWARE'S: Features of various RP software's like Magics, Mimics, Solid View, View Expert, 3 D View, Velocity 2, Rhino, STL View 3 Data Expert and 3 D doctor.

UNIT –VI

RP APPLICATIONS: Application in engineering, analysis and planning, aerospace industry, automotive industry, jewelry industry, coin industry, GIS application, arts and architecture. RP medical and bioengineering applications: planning and simulation of complex surgery, customized implants & prosthesis, design and production of medical devices, forensic science and anthropology, visualization of bimolecular.

TEXT BOOK:

1. Rapid prototyping: Principles and Applications - Chua C.K., Leong K.F. and LIM C.S, World Scientific publications.

REFERENCE BOOKS:

1. Rapid Manufacturing – D.T. Pham and S.S. Dimov, Springer.
2. Wholers Report 2000 – Terry Wohlers, Wohlers Associates.
3. Rapid Prototyping & Manufacturing – Paul F.Jacobs, ASME Press.

Course Outcomes:

The student shall be able to identify the use of Rapid Prototyping Techniques in the manufacturing of complex components that are otherwise very difficult to manufacture.

III Year – II SEMESTER

T	P	C
0	3	2

HEAT TRANSFER LAB

Objectives:

The laboratory course is aimed to provide the practical exposure to the students with regard to the determination of amount of heat exchange in various modes of heat transfer including condensation & boiling for several geometries.

1. Determination of overall heat transfer co-efficient of a composite slab.
2. Determination of heat transfer rate through a lagged pipe.
3. Determination of heat transfer rate through a concentric sphere.
4. Determination of thermal conductivity of a metal rod.
5. Determination of efficiency of a pin-fin.
6. Determination of heat transfer coefficient in forced convection.
7. Determination of heat transfer coefficient in natural convection.
8. Determination of effectiveness of parallel and counter flow heat exchangers.
9. Determination of emissivity of a given surface.
10. Determination of Stefan Boltzman constant.
11. Determination of heat transfer rate in drop and film wise condensation.
12. Determination of critical heat flux.
13. Demonstration of heat pipe.
14. Study of two – phase flow.

Outcomes: The student should be able to evaluate the amount of heat exchange for plane, cylindrical & spherical geometries and should be able to compare the performance of extended surfaces and heat exchangers.