IV Year – I SEMESTER

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RENEWABLE ENERGY SOURCES AND SYSTEMS

Preamble:

This course gives a flavor of renewable sources and systems to the students. It introduces solar energy its radiation, collection, storage and its applications. This covers generation, design, efficiency and characteristics of various renewable energy sources including solar, wind, hydro, biomass, fuel cells and geothermal systems.

Learning Objectives:

- To study the solar radiation data, extra terrestrial radiation, radiation on earth's surface.
- To study solar thermal collections.
- To study solar photo voltaic systems.
- To study maximum power point techniques in solar pv and wind.
- To study wind energy conversion systems, Betz coefficient, tip speed ratio.
- To study basic principle and working of hydro, tidal, biomass, fuel cell and geothermal systems.

UNIT–I:

Fundamentals of Energy Systems

Energy conservation principle – Energy scenario (world and India) – Solar radiation**:** Outside earth's atmosphere – Earth surface – Analysis of solar radiation data – Geometry – Radiation on tilted surfaces – Numerical problems.

UNIT–II:

Solar Thermal Systems

Liquid flat plate collections**:** Performance analysis – Transmissivity – Absorptivity product collector efficiency factor – Collector heat removal factor – Numerical problems. Introduction to solar air heaters – Concentrating collectors and solar pond.

UNIT–III:

Solar Photovoltaic Systems

Balance of systems – IV characteristics – System design**:** storage sizing – PV system sizing – Maximum power point techniques**:** Perturb and observe (P&O) technique – Hill climbing technique.

UNIT–IV:

Wind Energy

Wind patterns – Types of turbines – Kinetic energy of wind – Betz coefficient – Tip–speed ratio – Efficiency – Power output of wind turbine – Selection of generator(synchronous, induction) – Maximum power point tracking.

UNIT–V:

Hydro and Tidal power systems

Basic working principle – Classification of hydro systems**:** Large, small, micro – measurement of head and flow – Energy equation – Types of turbines – Numerical problems.

Tidal power – Basics – Kinetic energy equation – Numerical problems – Wave power – Basics – Kinetic energy equation.

UNIT–VI:

Biomass, fuel cells and geothermal systems

Biomass Energy**:** Fuel classification – Pyrolysis – Direct combustion of heat – Different digesters and sizing.

Fuel cell**:** Classification – Efficiency – VI characteristics.
Geothermal**:** Classification – Dry rock and acquifer – Energy analysis.

Learning Outcomes:

Student should be able to

- Analyze solar radiation data, extraterrestrial radiation, radiation on earth’s surface.
- Design solar thermal collections.
- Design solar photo voltaic systems.
- Develop maximum power point techniques in solar PV and wind.
- Explain wind energy conversion systems, Betz coefficient, tip speed ratio.
- Explain basic principle and working of hydro, tidal, biomass, fuel cell and geothermal systems.

Text Books:

1. Solar Energy**:** Principles of Thermal Collection and Storage, S. P. Sukhatme and J. K. Nayak, TMH, New Delhi, 3rd Edition.
2. Renewable Energy Resources, John Twidell and Tony Weir, Taylor and Francis -second edition, 2013.
3. Energy Science**:** Principles, Technologies and Impacts, John Andrews and Nick Jelly, Oxford.

Reference Books:

1. Renewable Energy- Edited by Godfrey Boyle-oxford university, press, 3rd edition, 2013.
2. Handbook of renewable technology Ahmed and Zobaa, Ramesh C Bansal, World scientific, Singapore.
3. Renewable Energy Technologies /Ramesh & Kumar /Narosa.
4. Renewable energy technologies – A practical guide for beginners – Chetong Singh Solanki, PHI.
5. Non conventional energy source –B.H. Khan- TMH-2nd edition.

IV Year – I SEMESTER	T	P	C
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HVAC & DC TRANSMISSION

Preamble:

With the increasing power generation in the country and long distance power transmission, it is necessary that power should be transmitted at extra and ultra high voltage. The topics dealt in this subject relate to phenomena associated with transmission line at higher voltages, equipments generating high voltage and power control strategy.

Learning Objectives:

- To understand the phenomena associated with transmission line, operating at extra high voltages. The unit gives detail analysis of several phenomena viz. electrostatic field, charges, voltage gradient and conductor configuration.
- The objective is to discuss phenomena of corona, losses, audible noise, radio interference and measurement of these quantities.
- To understand the phenomena of HVDC, HVDC equipment comparison with AC and the latest state of art in HVDC transmission.
- To understand method of conversion of AC to DC, performance of various level of pulse conversion and control characteristics of conversion. It also provides knowledge of effect of source inductance as well as method of power control.
- To understand the requirements of reactive power control and filtering technique in HVDC system.
- To understand the harmonics in AC side of power line in a HVDC system and design of filters for various levels of pulse conversion.

UNIT – I:

Introduction of EHV AC transmission

Necessity of EHV AC transmission – Advantages and problems – Power handling capacity and line losses – Mechanical considerations – Resistance of conductors –Electrostatics – Field of sphere gap – Field of line charges and properties – Charge ~ potential relations for multi–conductors – Surface voltage gradient on conductors – Bundle spacing and bundle radius –

Examples – Distribution of voltage gradient on sub conductors of bundle – Examples.

UNIT – II:

Corona effects

Power loss and audible noise (AN) – Corona loss formulae – Charge voltage diagram – Generation – Characteristics – Limits and measurements of AN – Relation between 1–phase and 3–phase AN levels – Examples – Radio interference (RI) – Corona pulses generation – Properties and limits – Frequency spectrum – Modes of propagation – Excitation function – Measurement of RI, RIV and excitation functions – Examples.

UNIT – III:

Basic Concepts of DC Transmission

Economics & Terminal equipment of HVDC transmission systems**:** Types of HVDC Links – Apparatus required for HVDC Systems – Comparison of AC &DC transmission – Application of DC Transmission System – Planning & Modern trends in DC transmission.

UNIT – IV:

Analysis of HVDC Converters and System Control

Choice of Converter configuration – Analysis of Graetz – Characteristics of 6 Pulse & 12 Pulse converters – Cases of two 3 phase converters in star – Star mode and their performance – Principal of DC Link Control – Converters Control Characteristics – Firing angle control – Current and extinction angle control – Effect of source inductance on the system – Starting and stopping of DC link – Power Control.

UNIT–V:

Reactive Power Control in HVDC

Reactive Power Requirements in steady state – Conventional control strategies –Alternate control strategies sources of reactive power – AC Filters – Shunt capacitors – Synchronous condensers.

UNIT – VI:

Harmonics and Filters

Generation of Harmonics – Characteristics harmonics – Calculation of AC Harmonics – Non–Characteristics harmonics – Adverse effects of harmonics – Calculation of voltage & current harmonics – Effect of Pulse number on harmonics. Types of AC filters, Design of Single tuned filters – Design of High pass filters.

Learning Outcomes:

- To be able to acquaint with HV transmission system with regard to power handling capacity, losses, conductor resistance and electrostatic field associate with HV. Further knowledge is gained in area of bundle conductor system to improve electrical and mechanical performance.
- To develop ability for determining corona, radio interference, audible noise generation and frequency spectrum for single and three phase transmission lines.
- To be able to acquire knowledge in transmission of HVDC power with regard to terminal equipments, type of HVDC connectivity and planning of HVDC system.
- To be able to develop knowledge with regard to choice of pulse conversion, control characteristic, firing angle control and effect of source impedance.
- To develop knowledge of reactive power requirements of conventional control, filters and reactive power compensation in AC. side of HVDC system.
- Able to calculate voltage and current harmonics, and design of filters for six and twelve pulse conversion.

Text Books:

1. HVDC Power Transmission Systems: Technology and system Interactions – by K.R.Padiyar, New Age International (P) Limited, and Publishers.
2. Direct Current Transmission – by E.W.Kimbark, John Wiley & Sons.
3. EHVAC Transmission Engineering by R. D. Begamudre, New Age International (P) Ltd.

Reference Books:

1. EHVAC and HVDC Transmission Engineering and Practice – S.Rao.
2. Power Transmission by Direct Current – by E.Uhlmann, B.S.Publications
3. HVDC Transmission – J. Arrillaga.

IV Year – I SEMESTER	T	P	C
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POWER SYSTEM OPERATION AND CONTROL

Preamble:

This subject deals with Economic operation of Power Systems, Hydrothermal scheduling and modeling of turbines, generators and automatic controllers. It emphasizes on single area and two area load frequency control and reactive power control.

Learning Objectives:

- To understand optimal dispatch of generation with and without losses.
- To study the optimal scheduling of hydro thermal systems.
- To study the optimal unit commitment problem.
- To study the load frequency control for single area system
- To study the PID controllers for single area system and two area system.
- To understand the reactive power control and compensation of transmission lines.

UNIT–I:

Economic Operation of Power Systems

Optimal operation of Generators in Thermal power stations, – Heat rate curve – Cost Curve – Incremental fuel and Production costs – Input–output characteristics – Optimum generation allocation with line losses neglected – Optimum generation allocation including the effect of transmission line losses – Loss Coefficients – General transmission line loss formula.

UNIT–II:

Hydrothermal Scheduling

Optimal scheduling of Hydrothermal System**:** Hydroelectric power plant models – Scheduling problems – Short term Hydrothermal scheduling problem.

UNIT–III:

Unit Commitment

Optimal unit commitment problem – Need for unit commitment – Constraints in unit commitment – Cost function formulation – Solution methods – Priority ordering – Dynamic programming.

UNIT–IV:

Load Frequency Control

Modeling of steam turbine – Generator – Mathematical modeling of speed governing system – Transfer function – Modeling of Hydro turbine – Necessity of keeping frequency constant – Definitions of Control area – Single area control – Block diagram representation of an isolated power system – Steady state analysis – Dynamic response – Uncontrolled case – Load frequency control of two area system – Uncontrolled case and controlled case – Tie–line bias control.

UNIT–V:

Load Frequency Controllers

Proportional plus Integral control of single area and its block diagram representation – Steady state response – Load Frequency Control and Economic dispatch control.

UNIT–VI:

Reactive Power Control

Overview of Reactive Power control – Reactive Power compensation in transmission systems – Advantages and disadvantages of different types of compensating equipment for transmission systems – Load compensation – Specifications of load compensator – Uncompensated and compensated transmission lines**:** Shunt and series compensation – Need for FACTS controllers.

Learning Outcomes:

- Able to compute optimal scheduling of Generators.
- Able to understand hydrothermal scheduling.
- Understand the unit commitment problem.
- Able to understand importance of the frequency.
- Understand importance of PID controllers in single area and two area systems.
- Will understand reactive power control and line power compensation.

Text Books:

1. Electric Energy systems Theory – by O.I.Elgerd, Tata McGraw–hill Publishing Company Ltd., Second edition.
2. Power System stability & control, Prabha Kundur,TMH
3. Modern Power System Analysis – by I.J.Nagrath & D.P.Kothari Tata Mc Graw – Hill Publishing Company Ltd, 2nd edition.

Reference Books:

1. Power System Analysis and Design by J.Duncan Glover and M.S.Sarma, THOMPSON, 3rd Edition.
2. Power System Analysis by Grainger and Stevenson, Tata McGraw Hill.
3. Power System Analysis by Hadi Saadat – TMH Edition.

IV Year – I SEMESTER	T	P	C
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Open Elective

ENERGY AUDIT, CONSERVATION & MANAGEMENT

Preamble:

This is an open elective course developed to cater current needs of the industry. This course covers topics such as energy conservation act and energy conservation. It also covers energy efficient lighting design, student will learn power factor improvement techniques, energy efficiency in HVAC systems. In addition, economic aspects such as payback period calculations, life cycle costing analysis is covered in this course.

Learning Objectives:

- To understand energy efficiency, scope, conservation and technologies.
- To design energy efficient lighting systems.
- To estimate/calculate power factor of systems and propose suitable compensation techniques.
- To understand energy conservation in HVAC systems.
- To calculate life cycle costing analysis and return on investment on energy efficient technologies.

Unit–I:

Basic Principles of Energy Audit and management

Energy audit – Definitions – Concept – Types of audit – Energy index – Cost index – Pie charts – Sankey diagrams – Load profiles – Energy conservation schemes and energy saving potential – Numerical problems – Principles of energy management – Initiating, planning, controlling, promoting, monitoring, reporting – Energy manager – Qualities and functions – Language – Questionnaire – Check list for top management.

Unit–II:

Lighting

Modification of existing systems – Replacement of existing systems – Priorities**:** Definition of terms and units – Luminous efficiency – Polar curve – Calculation of illumination level – Illumination of inclined surface to beam

– Luminance or brightness – Types of lamps – Types of lighting – Electric lighting fittings (luminaries) – Flood lighting – White light LED and conducting Polymers – Energy conservation measures.

Unit–III:

Power Factor and energy instruments

Power factor – Methods of improvement – Location of capacitors – Power factor with non linear loads – Effect of harmonics on Power factor – Numerical problems. Energy Instruments – Watt–hour meter – Data loggers – Thermocouples – Pyrometers – Lux meters – Tong testers – Power analyzer.

Unit–IV:

Space Heating and Ventilation

Ventilation – Air–Conditioning (HVAC) and Water Heating**:** Introduction – Heating of buildings – Transfer of Heat–Space heating methods – Ventilation and air–conditioning – Insulation–Cooling load – Electric water heating systems – Energy conservation methods.

Unit–V

Economic Aspects and Analysis

Economics Analysis – Depreciation Methods – Time value of money – Rate of return – Present worth method – Replacement analysis – Life cycle costing analysis – Energy efficient motors (basic concepts).

Unit–VI:

Computation of Economic Aspects

Calculation of simple payback method – Net present worth method – Power factor correction – Lighting – Applications of life cycle costing analysis – Return on investment.

Learning Outcomes:

Student will be able to

- Explain energy efficiency, conservation and various technologies.
- Design energy efficient lighting systems.
- Calculate power factor of systems and propose suitable compensation techniques.
- Explain energy conservation in HVAC systems.
- Calculate life cycle costing analysis and return on investment on energy efficient technologies.

Text Books:

1. Energy management by W.R. Murphy & G. Mckay Butter worth, Elsevier publications. 2012
2. Energy efficient electric motors by John .C. Andreas, Marcel Dekker Inc Ltd–2nd edition, 1995

Reference Books:

1. Electric Energy Utilization and Conservation by S C Tripathy, Tata McGraw hill publishing company Ltd. New Delhi.
2. Energy management by Paul o' Callaghan, Mc–Graw Hill Book company–1st edition, 1998.
3. Energy management hand book by W.C.Turner, John wiley and sons.
4. Energy management and conservation –k v Sharma and pvenkata seshaiah-I K International Publishing House pvt.ltd,2011.
5. http://www.energymanagertraining.com/download/Gazette_of_IndiaPartIISecI-37_25-08-2010.pdf

Note : This Elective can be offered to Students of All Branches including EEE.

INSTRUMENTATION
(Open Elective)

Preamble:

Electrical and Electronic Instrumentation plays a key role in the industry. With the advancement of technology day to day manual maintenance is replaced by simply monitoring using various instruments. Thus this course plays very important role in overall maintenance of the industry.

Learning Objectives:

- To study various types of signals and their representation.
- To study various types of transducers: Electrical, Mechanical, Electromechanical, Optical etc.
- To study and measure the various types of Non–electrical quantities.
- To study various types of digital voltmeters
- To study the working principles of various types of oscilloscopes and their applications.
- To study various types of signal analyzers.

UNIT–I:

Signals and their representation

Measuring Systems, Performance Characteristics, – Static characteristics – Dynamic Characteristics – Errors in Measurement – Gross Errors – Systematic Errors – Statistical analysis of random errors – Signal and their representation – Standard test, periodic, aperiodic, modulated signal – Sampled data pulse modulation and pulse code modulation.

UNIT–II:

Transducers

Definition of transducers – Classification of transducers – Advantages of Electrical transducers – Characteristics and choice of transducers – Principle operation of resistor, inductor, LVDT and capacitor transducers – LVDT Applications – Strain gauge and its principle of operation – Guage factor – Thermistors – Thermocouples – Synchros – Piezo electric transducers – Photo diodes.

UNIT–III:

Measurement of Non–Electrical Quantities

Measurement of strain – Gauge Sensitivity – Displacement – Velocity – Angular Velocity – Acceleration – Force – Torque – Measurement of Temperature, Pressure, Vacuum, Flow, Liquid level.

UNIT–IV:

Digital Voltmeters

Digital voltmeters – Successive approximation, ramp, dual–Slope integration continuous balance type – Micro processor based ramp type – DVM digital frequency meter – Digital phase angle meter.

UNIT–V:

Oscilloscope

Cathode ray oscilloscope – Time base generator – Horizantal and vertical amplifiers – Measurement of phase and frequency – Lissajous patterns – Sampling oscilloscope – Analog and digital type data loger – Transient recorder.

UNIT–VI:

Signal Analyzers

Wave Analyzers – Frequency selective analyzers – Heterodyne – Application of Wave analyzers – Harmonic Analyzers – Total Harmonic distortion – Spectrum analyzers – Basic spectrum analyzers – Spectral displays – Vector impedance meter – Q meter – Peak reading and RMS voltmeters.

Learning Outcomes:

- Able to represent various types of signals .
- Acquire proper knowledge to use various types of Transducers.
- Able to monitor and measure various parameters such as strain, velocity, temperature, pressure etc.
- Acquire proper knowledge and working principle of various types of digital voltmeters.
- Able to measure various parameter like phase and frequency of a signal with the help of CRO.
- Acquire proper knowledge and able to handle various types of signal analyzers.

Text Books:

1. Electronic Instrumentation–by H.S.Kalsi Tata MCGraw–Hill Edition, 1995.
2. A course in Electrical and Electronic Measurements and Instrumentation, A.K. Sawhney, Dhanpatrai& Co.

Reference Books:

1. Measurement and Instrumentation theory and application, Alan S.Morris and Reza Langari, Elsevier
2. Measurements Systems, Applications and Design – by D O Doeblin
3. Principles of Measurement and Instrumentation – by A.S Morris, Pearson / Prentice Hall ofIndia
4. Modern Electronic Instrumentation and Measurement techniques – by A.D Helfrickand W.D. Cooper, Pearson/Prentice Hall of India.
4. Transducers and Instrumentation by D.V.S Murthy, Prentice Hall of India.

Note : This Elective can be offered to Students of All Branches including EEE.

NON–CONVENTIONAL SOURCES OF ENERGY
(Open Elective)

Preamble:

This course gives a flavor of non–conventional sources of energy to the students. It introduces solar energy its radiation, collection, storage and its applications. This covers generation, design, efficiency and characteristics of various non–conventional energy sources including solar, wind, hydro, biomass, fuel cells and geothermal systems.

Learning Objectives

- To study the solar radiation data, extraterrestrial radiation, radiation on earth's surface.
- To study solar thermal collections.
- To study solar photo voltaic systems.
- To study maximum power point techniques in solar pv and wind.
- To study wind energy conversion systems, Betz coefficient , tip speed ratio.
- To study basic principle and working of hydro, tidal, biomass, fuel cell and geothermal systems.

UNIT–I:

Fundamentals of Energy Systems

Energy conservation principle – Energy scenario (world and India) – Solar radiation**:** Outside earth's atmosphere – Earth surface – Analysis of solar radiation data – Geometry – Radiation on tilted surfaces – Numerical problems.

UNIT–II:

Solar Thermal Systems

Liquid flat plate collections**:** Performance analysis – Transmissivity – Absorptivity – Product collector efficiency factor – Collector heat removal factor – Numerical problems – Introduction to solar air heaters – Concentrating collectors and solar pond.

UNIT–III:

Solar Photovoltaic Systems

Balance of systems – IV characteristics – System design**:** Storage sizing, PV system sizing, Maximum power point techniques**:** Perturb and observe (P&O) technique – Hill climbing technique.

UNIT–IV:

Wind Energy

Wind patterns – Types of turbines – Kinetic energy of wind – Betz coefficient – Tip–speed ratio – efficiency – Power output of wind turbine – Selection of generator(synchronous, induction) – Maximum power point tracking.

UNIT–V:

Hydro and Tidal power systems

Basic working principle – Classification of hydro systems**:** large, small, micro – Measurement of head and flow – Energy equation – Types of turbines – Numerical problems.
Tidal power – Basics – Kinetic energy equation – Numerical problems – Wave power – Basics – Kinetic energy equation.

UNIT–VI:

Biomass, fuel cells and geothermal systems

Biomass Energy**:** Fuel classification – Pyrolysis – Direct combustion of heat – Different digesters and sizing.
Fuel cell**:** classification – Efficiency – VI characteristics.
Geothermal**:** classification – Dry rock and acquifer – Energy analysis.

Learning Outcomes:

Student should be able to

- Analyze solar radiation data, extraterrestrial radiation, radiation on earth's surface.
- Design solar thermal collections.
- Design solar photo voltaic systems.
- Develop maximum power point techniques in solar PV and wind.
- Explain wind energy conversion systems, Betz coefficient , tip speed ratio.
- Explain basic principle and working of hydro, tidal, biomass ,fuel cell and geothermal systems.

Text Books:

1. Solar Energy: Principles of Thermal Collection and Storage, S. P. Sukhatme and J. K. Nayak, TMH, New Delhi, 3rd Edition.
2. Renewable Energy Resources, John Twidell and Tony Weir, Taylor and Francis.

3. Energy Science: Principles, Technologies and Impacts, John Andrews and Nick Jelly, Oxford.

Reference Books:

1. Handbook of renewable technology Ahmed and Zobaa, Ramesh C Bansal,World scientific, Singapore.
2. Renewable Energy Technologies /Ramesh & Kumar /Narosa.
3. Renewable energy technologies – A practical guide for beginners – Chetong Singh Solanki, PHI.

Note : This Elective can be offered to Students of All Branches including EEE.

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OPTIMIZATION TECHNIQUES
(Open Elective)

Preamble:

Optimization techniques have gained importance to solve many engineering design problems by developing linear and nonlinear mathematical models. The aim of this course is to educate the student to develop a mathematical model by defining an objective function and constraints in terms of design variables and then apply a particular mathematical programming technique. This course covers classical optimization techniques, linear programming, nonlinear programming and dynamic programming techniques.

Learning Objectives:

1. To define an objective function and constraint functions in terms of design variables, and then state the optimization problem.
2. To state single variable and multi variable optimization problems, without and with constraints.
3. To explain linear programming technique to an optimization problem, define slack and surplus variables, by using Simplex method.
4. To state transportation and assignment problem as a linear programming problem to determine optimality conditions by using Simplex method.
5. To study and explain nonlinear programming techniques, unconstrained or constrained, and define exterior and interior penalty functions for optimization problems.
6. To explain Dynamic programming technique as a powerful tool for making a sequence of interrelated decisions.

UNIT – I:

Introduction and Classical Optimization Techniques:

Statement of an Optimization problem – design vector – design constraints – constraint surface – objective function – objective function surfaces – classification of Optimization problems.

UNIT – II:

Classical Optimization Techniques

Single variable Optimization – multi variable Optimization without constraints – necessary and sufficient conditions for minimum/maximum – multivariable Optimization with equality constraints. Solution by method of

Lagrange multipliers – multivariable Optimization with inequality constraints – Kuhn – Tucker conditions.

UNIT – III:

Linear Programming

Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm - Duality in Linear Programming – Dual Simplex method.

UNIT – IV:

Transportation Problem

Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems – Special cases in transportation problem.

UNIT – V:

Nonlinear Programming:

Unconstrained cases - One – dimensional minimization methods: Classification, Fibonacci method and Quadratic interpolation method - Univariate method, Powell's method and steepest descent method.

Constrained cases - Characteristics of a constrained problem, Classification, Basic approach of Penalty Function method; Basic approaches of Interior and Exterior penalty function methods. Introduction to convex Programming Problem.

UNIT – VI:

Dynamic Programming:

Dynamic programming multistage decision processes – types – concept of sub optimization and the principle of optimality – computational procedure in dynamic programming – examples illustrating the calculus method of solution - examples illustrating the tabular method of solution.

Learning Outcomes:

The student should be able to:

1. State and formulate the optimization problem, without and with constraints, by using design variables from an engineering design problem.

2. Apply classical optimization techniques to minimize or maximize a multi-variable objective function, without or with constraints, and arrive at an optimal solution.
3. Formulate a mathematical model and apply linear programming technique by using Simplex method. Also extend the concept of dual Simplex method for optimal solutions.
4. Solve transportation and assignment problem by using Linear programming Simplex method.
5. Apply gradient and non-gradient methods to nonlinear optimization problems and use interior or exterior penalty functions for the constraints to derive the optimal solutions.
6. Formulate and apply Dynamic programming technique to inventory control, production planning, engineering design problems etc. to reach a final optimal solution from the current optimal solution.

Text Books:

1. “Engineering optimization: Theory and practice”-by S. S.Rao, New Age International (P) Limited, 3rd edition, 1998.
2. “Introductory Operations Research” by H.S. Kasene & K.D. Kumar, Springer (India), Pvt. LTd.

Reference Books:

1. “Optimization Methods in Operations Research and systems Analysis” – by K.V. Mital and C. Mohan, New Age International (P) Limited, Publishers, 3rd edition, 1996.
2. Operations Research – by Dr. S.D.Sharma, Kedarnath, Ramnath & Co
3. “Operations Research: An Introduction” – by H.A.Taha, PHI Pvt. Ltd., 6th edition
4. Linear Programming–by G.Hadley.

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Note : This Elective can be offered to Students of All Branches except EEE.

IV Year – I SEMESTER

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Elective – I

VLSI DESIGN

Preamble:

In the recent times fabrication technology is revolutionized and especially LSI has become so dense that on a single IC tens and thousands of transistors are placed. Thus integrated circuits have become integrated systems and the development of fabrication technology VLSI plays very important role.

Learning Objectives:

- To provide the basic fundamentals of fabrication technology, generations of IC and speed, power consumptions of various fabrication technologies.
- To understand the knowledge of electrical properties of MOS circuits.
- To learn the design concepts of stick diagrams, layouts for various MOS technologies.
- To understand the concepts of design rules, scaling, subsystem design semiconductor IC design.
- To understand the synthesis, simulation design verification tools, CMOS testing.

UNIT –I

Introduction

Introduction to IC technology – The IC era – MOS and related VLSI technology – Basic MOS transistors – Enhancement and depletion modes of transistor action – IC production process – MOS and CMOS fabrication process – BiCMOS technology – Comparison b/w CMOS and bipolar technologies.

UNIT – II

Basic electrical properties of MOS and BiCMOS circuits

I_{ds}–V_{ds} relationships – Aspects of MOS transistor threshold voltage – MOS Trans–conductance and output conductance – MOS Transistor – Figure of merit – The pMOS transistor – The nMOS inverter – Determination of pull–up to pull–down ratio for nMOS inverter driven by another nMOS inverter for an nMOS inverter driven through one or more pass Transistors – Alternative forms of pull up – The CMOS Inverter MOS transistor Circuit model – Bi–CMOS Inverters.

UNIT – III

MOS and BiCOMS circuit design processes

MOS layers – Stick diagrams – Design rules and layout – General observation on the design rules, 2µm double metal, double poly – CMOS/BiCMOS rules, 1.2µm Double metal, Double poly CMOS rules – Layout diagrams of NAND and NOR gates and CMOS inverter – Symbolic Diagrams – Translation to Mask Form.

UNIT – IV

Basic circuit concepts

Sheet resistance – Sheet resistance concept applied to MOS transistor and inverters – Area capacitance of layers – Standard unit of capacitance – Some area capacitance calculations – The delay unit – Inverter delays – Driving large capacitive loads – Propagations Delays – Wiring Capacitance – Fan–in and Fan–out characteristics – Choice of layers – Transistor switches – Realization of gates using nMOS, pMOS and CMOS technologies.

UNIT – V

Scaling of MOS circuit

Scaling models and scaling factors – Scaling factors for device parameters – Limitations of scaling – Limits due to sub threshold currents – Limits on logic level and supply voltage due to noise – Limits due to current density – Some architectural Issues – Introduction to switch logic and gate logic.

UNIT – VI

Digital design using HDL

Digital system design process – VLSI Circuit Design Process – Hardware simulation – Hardware Synthesis – History of VHDL – VHDL requirements – Levels of abstraction – Elements of VHDL – Packages – Libraries and bindings – Objects and classes – Variable assignments – Sequential statements – Usage of subprograms – Comparison of VHDL and verilog HDL.

VHDL MODELLING

Simulation – Logic Synthesis – Inside a logic synthesizer – Constraints – Technology libraries – VHDL and logic synthesis – Functional gate – Level verification – Place and route – Post layout timing simulation – Static timing

– Major net list formats for design representation – VHDL synthesis – Programming approach.

Learning Outcomes

- Ability to demonstrate the fundamentals of IC technology such as various MOS fabrication technologies.
- Ability to calculate electrical properties of MOS circuits such as Ids – Vds relationship, Vt, gm, gds, figure of merit, sheet resistance, area capacitance.
- Ability to demonstrate semi conductor IC design such as PLA's, PAL, FPGA, CPLS's design.
- Ability to demonstrate VHDL synthesis, simulation, design capture tools design verification tools, CMOS testing.

Text Books:

1. Essentials of VLSI Circuits and Systems–Kamran Eshraghian, Douglas and A.Pucknell and Sholeh Eshraghian, Prentice–Hall of India Private Limited, 2005 Edition.
2. VLSI Design–K. Lal Kishor and V.S.V.Prabhakar, I.K. International Publishing House Private Limited, 2009 First Edition.
3. VLSI Design–A.Shanthi and A.Kavitha, New Age International Private Limited, 2006 First Edition.

References Books:

1. VLSI Design By Debaprasad Das, Oxford University Press,2010.
2. VLSI Design By A.Albert Raj & T. Latha, PHI Learning Private Limited, 2010.

ELECTRICAL DISTRIBUTION SYSTEMS
(ELECTIVE–I)

Preamble:

This subject deals with the general concept of distribution system, substations and feeders as well as discusses distribution system analysis, protection and coordination, voltage control and power factor improvement.

Learning Objectives

- To study different factors of Distribution system.
- To study and design the substations and distribution systems.
- To study the determination of voltage drop and power loss.
- To study the distribution system protection and its coordination.
- To study the effect of compensation on p.f improvement.
- To study the effect of voltage control on distribution system.

UNIT – I:

General Concepts

Introduction to distribution systems, Load modeling and characteristics – Coincidence factor – Contribution factor loss factor – Relationship between the load factor and loss factor – Classification of loads (Residential, commercial, Agricultural and Industrial) and their characteristics.

UNIT – II:

Substations

Location of substations**:** Rating of distribution substation – Service area within primary feeders – Benefits derived through optimal location of substations.

Distribution Feeders

Design Considerations of distribution feeders**:** Radial and loop types of primary feeders – Voltage levels – Feeder loading – Basic design practice of the secondary distribution system.

UNIT – III:

System Analysis

Voltage drop and power–loss calculations**:** Derivation for voltage drop and power loss in lines – Manual methods of solution for radial networks – Three phase balanced primary lines.

UNIT – IV:

Protection

Objectives of distribution system protection – Types of common faults and procedure for fault calculations – Protective devices**:** Principle of operation of fuses – Circuit reclosures – Line sectionalizes and circuit breakers.

Coordination

Coordination of protective devices**:** General coordination procedure – Residual current circuit breaker RCCB (Wikipedia).

UNIT – V:

Compensation for Power Factor Improvement

Capacitive compensation for power–factor control – Different types of power capacitors – shunt and series capacitors – Effect of shunt capacitors (Fixed and switched) – Power factor correction – Capacitor allocation – Economic justification – Procedure to determine the best capacitor location.

UNIT – VI:

Voltage Control

Voltage Control**:** Equipment for voltage control – Effect of series capacitors – Effect of AVB/AVR –Line drop compensation.

Learning Outcomes:

- Able to understand the various factors of distribution system.
- Able to design the substation and feeders.
- Able to determine the voltage drop and power loss
- Able to understand the protection and its coordination.
- Able to understand the effect of compensation on p.f improvement.
- Able to understand the effect of voltage, current distribution system performance.

Text Book:

1. "Electric Power Distribution system, Engineering" – by TuranGonen, McGraw–hill Book Company.

Reference Books:

1. Electrical Distribution Systems by Dale R.Patrick and Stephen W.Fardo, CRC press
2. Electric Power Distribution – by A.S. Pabla, Tata McGraw–hill Publishing company, 4th edition, 1997.
3. Electrical Power Distribution Systems by V.Kamaraju, Right Publishers.

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OPTIMIZATION TECHNIQUES
(Elective-I)

Preamble:

Optimization techniques have gained importance to solve many engineering design problems by developing linear and nonlinear mathematical models. The aim of this course is to educate the student to develop a mathematical model by defining an objective function and constraints in terms of design variables and then apply a particular mathematical programming technique. This course covers classical optimization techniques, linear programming, nonlinear programming and dynamic programming techniques.

Learning Objectives:

1. To define an objective function and constraint functions in terms of design variables, and then state the optimization problem.
2. To state single variable and multi variable optimization problems, without and with constraints.
3. To explain linear programming technique to an optimization problem, define slack and surplus variables, by using Simplex method.
4. To state transportation and assignment problem as a linear programming problem to determine optimality conditions by using Simplex method.
5. To study and explain nonlinear programming techniques, unconstrained or constrained, and define exterior and interior penalty functions for optimization problems.
6. To explain Dynamic programming technique as a powerful tool for making a sequence of interrelated decisions.

UNIT – I:

Introduction and Classical Optimization Techniques:

Statement of an Optimization problem – design vector – design constraints – constraint surface – objective function – objective function surfaces – classification of Optimization problems.

UNIT – II:

Classical Optimization Techniques

Single variable Optimization – multi variable Optimization without constraints – necessary and sufficient conditions for minimum/maximum – multivariable Optimization with equality constraints. Solution by method of

Lagrange multipliers – multivariable Optimization with inequality constraints – Kuhn – Tucker conditions.

UNIT – III:

Linear Programming

Standard form of a linear programming problem – geometry of linear programming problems – definitions and theorems – solution of a system of linear simultaneous equations – pivotal reduction of a general system of equations – motivation to the simplex method – simplex algorithm - Duality in Linear Programming – Dual Simplex method.

UNIT – IV:

Transportation Problem

Finding initial basic feasible solution by north – west corner rule, least cost method and Vogel's approximation method – testing for optimality of balanced transportation problems – Special cases in transportation problem.

UNIT – V:

Nonlinear Programming:

Unconstrained cases - One – dimensional minimization methods: Classification, Fibonacci method and Quadratic interpolation method - Univariate method, Powell's method and steepest descent method.

Constrained cases - Characteristics of a constrained problem, Classification, Basic approach of Penalty Function method; Basic approaches of Interior and Exterior penalty function methods. Introduction to convex Programming Problem.

UNIT – VI:

Dynamic Programming:

Dynamic programming multistage decision processes – types – concept of sub optimization and the principle of optimality – computational procedure in dynamic programming – examples illustrating the calculus method of solution - examples illustrating the tabular method of solution.

Learning Outcomes:

The student should be able to:

1. State and formulate the optimization problem, without and with constraints, by using design variables from an engineering design problem.

2. Apply classical optimization techniques to minimize or maximize a multi-variable objective function, without or with constraints, and arrive at an optimal solution.
3. Formulate a mathematical model and apply linear programming technique by using Simplex method. Also extend the concept of dual Simplex method for optimal solutions.
4. Solve transportation and assignment problem by using Linear programming Simplex method.
5. Apply gradient and non-gradient methods to nonlinear optimization problems and use interior or exterior penalty functions for the constraints to derive the optimal solutions.
6. Formulate and apply Dynamic programming technique to inventory control, production planning, engineering design problems etc. to reach a final optimal solution from the current optimal solution.

Text Books:

1. “Engineering optimization : Theory and practice”-by S. S.Rao, New Age International (P) Limited, 3rd edition, 1998.
2. “Introductory Operations Research” by H.S. Kasene & K.D. Kumar, Springer (India), Pvt. LTd.

Reference Books:

1. “Optimization Methods in Operations Research and systems Analysis” – by K.V. Mital and C. Mohan, New Age International (P) Limited, Publishers, 3rd edition, 1996.
2. Operations Research – by Dr. S.D.Sharma, Kedarnath, Ramnath & Co
3. “Operations Research : An Introduction” – by H.A.Taha,PHI pvt. Ltd., 6th edition
4. Linear Programming–by G. Hadley.

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	T	P	C
IV Year – I SEMESTER	**0**	**3**	**2**

MICROPROCESSORS AND MICROCONTROLLERS LAB

Learning Objectives:

- To study programming based on 8086 microprocessor and 8051 microcontroller.
- To study 8056 microprocessor based ALP using arithmetic, logical and shift operations.
- To study modular and Dos/Bios programming using 8086 micro processor.
- To study to interface 8086 with I/O and other devices.
- To study parallel and serial communication using 8051 micro controller.

Any 8 of the following experiments are to be conducted :

I. Microprocessor 8086 :

Introduction to MASM/TASM.

1. Arithmetic operation – Multi byte addition and subtraction, multiplication and division – Signed and unsigned arithmetic operation, ASCII – Arithmetic operation.
2. Logic operations – Shift and rotate – Converting packed BCD to unpacked BCD, BCD to ASCII conversion.
3. By using string operation and Instruction prefix**:** Move block, Reverse string Sorting, Inserting, Deleting, Length of the string, String comparison.
4. Modular Program: Procedure, Near and Far implementation, Recursion.
5. Dos/BIOS programming: Reading keyboard (Buffered with and without echo) – Display characters, Strings.
6. Interfacing 8255–PPI
7. Programs using special instructions like swap, bit/byte, set/reset etc.
8. Programs based on short, page, absolute addressing.
9. Interfacing 8259 – Interrupt Controller.

10. Interfacing 8279 – Keyboard Display.
11. Stepper motor control using 8253/8255.

Any 2 of the following experiments are to be conducted:

Microcontroller 8051

12. Reading and Writing on a parallel port.
13. Timer in different modes.
14. Serial communication implementation.
15. Understanding three memory areas of 00 – FF (Programs using above areas).

    Using external interrupts.

Learning Outcomes:

- Will be able to write assembly language program using 8086 micro based on arithmetic, logical, and shift operations.
- Will be able to do modular and Dos/Bios programming using 8086 micro processor.
- Will be able to interface 8086 with I/O and other devices.
- Will be able to do parallel and serial communication using 8051 micro controllers.

IV Year – I SEMESTER

T	P	C
0	**3**	**2**

ELECTRICAL SIMULATION LAB

Learning objectives:

- To simulate integrator circuit, differentiator circuit, Boost converter, Buck converter, full convertor and PWM inverter.
- To simulate transmission line by incorporating line, load and transformer models.
- To perform transient analysis of RLC circuit and single machine connected to infinite bus (SMIB).
- To find load flow solution for a transmission network with Newton–Rampson method.

Following experiments are to be conducted:

1. Simulation of transient response of RLC circuits
   a. Response to pulse input
   b. Response to step input
   c. Response to sinusoidal input
2. Analysis of three phase circuit representing the generator transmission line and load. Plot three phase currents & neutral current.
3. Simulation of single–phase full converter using RLE loads and single phase AC voltage controller using RL loads.
4. Plotting of Bode plots, root locus and nyquist plots for the transfer functions of systems up to 5^{th} order.
5. Power system load flow using Newton–Raphson technique.
6. Simulation of Boost and Buck converters.
7. Integrator & Differentiator circuits using op–amp.
8. Simulation of D.C separately excited motor using transfer function approach.

Any 2 of the following experiments are to be conducted:

1. Modeling of transformer and simulation of lossy transmission line.
2. Simulation of single phase inverter with PWM control.
3. Simulation of three phase full converter using MOSFET and IGBTs.
4. Transient analysis of single machine connected to infinite bus (SMIB).

Learning outcomes:

- Able to simulate integrator circuit, differentiator circuit, Boost converter, Buck converter, full convertor and PWM inverter.
- Able to simulate transmission line by incorporating line, load and transformer models.
- Able to perform transient analysis of RLC circuit and single machine connected to infinite bus (SMIB).
- Able to find load flow solution for a transmission network with Newton–Rampson method.

Reference Books:

1. "Simulation of Power Electronic Circuit", by M.B. Patil, V.Ramanarayan, V.T. Ranganathan. Narosha, 2009.
2. Pspice for circuits and electronics using PSPICE – by M.H.Rashid, M/s PHI Publications.
3. Pspice A/D user`s manual – Microsim, USA.
4. Pspice reference guide – Microsim, USA.
5. MATLAB user`s manual – Mathworks, USA.
6. MATLAB – control system tool box – Mathworks, USA.
7. SIMULINK user`s manual – Mathworks, USA.
8. EMTP User`s Manual.
9. SEQUEL– A public domain circuit simulator available at www.ee.iitb.ac.in/~sequel.

IV Year – I SEMESTER	T	P	C
	0	3	2

POWER SYSTEMS LAB

Learning Objectives:

To impart the practical knowledge of functioning of various power system components and determination of various parameters and simulation of load flows, transient stability, LFC and Economic dispatch.

Any 10 of the Following experiments are to be conducted:

1. Sequence impedances of 3 phase Transformer.
2. Sequence impedances of 3 phase Alternator by Fault Analysis.
3. Sequence impedances of 3 phase Alternator by Direct method.
4. ABCD parameters of Transmission network.
5. Power Angle Characteristics of 3phase Alternator with infinite bus bars.
6. Dielectric strength of Transformer oil.
7. Calibration of Tong Tester.

8&9. Load flow studies any two methods.

10. Transient Stability Analysis
11. Load frequency control without control
12. Load frequency control with control
13. Economic load dispatch without losses
14. Economic load dispatch with losses.

Learning Outcomes:

The student is able to determine the parameters of various power system components which are frequently occur in power system studies and he can execute energy management systems functions at load dispatch centre.

IV Year – II SEMESTER	T	P	C
	3+1	0	3

DIGITAL CONTROL SYSTEMS

Preamble:

In recent years digital controllers have become popular due to their capability of accurately performing complex computations at high speeds and versatility in leading non linear control systems. In this context, this course focuses on the analysis and design of digital control systems.

Learning objectives:

- To understand the concepts of digital control systems and assemble various components associated with it. Advantages compared to the analog type.
- The theory of z–transformations and application for the mathematical analysis of digital control systems.
- To represent the discrete–time systems in state–space model and evaluation of state transition matrix.
- To examine the stability of the system using different tests.
- To study the conventional method of analyzing digital control systems in the w–plane.
- To study the design of state feedback control by "the pole placement method."

UNIT – I:

Introduction and signal processing

Introduction to analog and digital control systems – Advantages of digital systems – Typical examples – Signals and processing – Sample and hold devices – Sampling theorem and data reconstruction – Frequency domain characteristics of zero order hold.

UNIT–II:

Z–transformations

Z–Transforms – Theorems – Finding inverse z–transforms – Formulation of difference equations and solving – Block diagram representation – Pulse transfer functions and finding open loop and closed loop responses.

UNIT–III:

State space analysis and the concepts of Controllability and observability

State Space Representation of discrete time systems – State transition matrix and methods of evaluation – Discretization of continuous – Time state equations – Concepts of controllability and observability – Tests (without proof).

UNIT – IV:

Stability analysis

Mapping between the S–Plane and the Z–Plane – Primary strips and Complementary Strips – Stability criterion – Modified routh's stability criterion and jury's stability test.

UNIT – V:

Design of discrete–time control systems by conventional methods

Transient and steady state specifications – Design using frequency response in the w–plane for lag and led compensators – Root locus technique in the z–plane.

UNIT – VI:

State feedback controllers:

Design of state feedback controller through pole placement – Necessary and sufficient conditions – Ackerman's formula.

Learning outcomes:

- The students learn the advantages of discrete time control systems and the "know how" of various associated accessories.
- The learner understand z–transformations and their role in the mathematical analysis of different systems(like laplace transforms in analog systems).
- The stability criterion for digital systems and methods adopted for testing the same are explained.
- Finally, the conventional and state–space methods of design are also introduced.

Text Book:

1. Discrete–Time Control systems – K. Ogata, Pearson Education/PHI, 2nd Edition

Reference Books:

1. Digital Control Systems, Kuo, Oxford University Press, 2nd Edition, 2003.
2. Digital Control and State Variable Methods by M.Gopal, TMH

IV Year – II SEMESTER	T	P	C
	3+1	0	3

ELECTIVE – II

ADVANCED CONTROL SYSTEMS

Preamble:

This subject aims to study state space, describing function, phase plane and stability analysis including controllability and observability. It also deals with modern control and optimal control systems.

Learning Objectives:

- Review of the state space representation of a control system**:** Formulation of different models from the signal flow graph, diagonalization.
- To introduce the concept of controllability and observability. Design by pole placement technique.
- Analysis of a nonlinear system using Describing function approach and Phase plane analysis.
- The Lypanov's method of stability analysis of a system.
- Formulation of Euler Laugrange equation for the optimization of typical functionals and solutions.
- Formulation of linear quadratic optimal regulator (LQR) problem by parameter adjustment and solving riccatti equation.

UNIT – I:

State space analysis

State Space Representation – Solution of state equation – State transition matrix, –Canonical forms – Controllable canonical form – Observable canonical form, Jordan Canonical Form.

UNIT – II:

Controllability, observability and design of pole placement

Tests for controllability and observability for continuous time systems – Time varying case – Minimum energy control – Time invariant case – Principle of duality – Controllability and observability form Jordan canonical form and other canonical forms – Effect of state feedback on controllability and observability – Design of state feedback control through pole placement.

UNIT – III:

Describing function analysis

Introduction to nonlinear systems, Types of nonlinearities, describing functions, Introduction to phase–plane analysis.

UNIT–IV:

Stability analysis

Stability in the sense of Lyapunov – Lyapunov's stability and Lypanov's instability theorems – Direct method of Lypanov for the linear and nonlinear continuous time autonomous systems.

UNIT–V:

Calculus of variations

Minimization of functional of single function – Constrained minimization – Minimum principle – Control variable inequality constraints – Control and state variable inequality constraints – Euler lagrangine equation.

UNIT –VI:

Optimal control

Linear quadratic optimal regulator (LQR) problem formulation – Optimal regulator design by parameter adjustment (Lyapunov method) – Optimal regulator design by continuous time algebraic riccatti equation (CARE) - Optimal controller design using LQG framework.

Learning Outcomes:

- State space representation of control system and formulation of different state models are reviewed.
- Able to design of control system using the pole placement technique is given after introducing the concept of controllability and observability.
- Able to analyse of nonlinear system using the describing function technique and phase plane analysis.
- Able to analyse the stability analysis using lypnov method.
- Minimization of functionals using calculus of variation studied.
- Able to formulate andsolve the LQR problem and riccatti equation.

Text Books:

- Modern Control Engineering – by K. Ogata, Prentice Hall of India, 3rd edition, 1998
- Automatic Control Systems by B.C. Kuo, Prentice Hall Publication

Reference Books:

1. Modern Control System Theory – by M. Gopal, New Age International Publishers, 2nd edition, 1996
2. Control Systems Engineering by I.J. Nagarath and M.Gopal, New Age International (P) Ltd.
3. Digital Control and State Variable Methods – by M. Gopal, Tata Mc Graw– Hill Companies, 1997.
4. Systems and Control by Stainslaw H. Zak , Oxford Press, 2003.
5. Optimal control theory: an Introduction by Donald E.Kirk by Dover publications.

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HIGH VOLTAGE ENGINEERING
(ELECTIVE – II)

Preamble:

With the growth of power, HV power transmission has become an important subject. The performance of generating equipment requires knowledge of different phenomena occurring at higher voltage. Thus evaluations of various insulating materials are required for protection of HV equipments. Keeping this in view the course is designed to understand various phenomena related to breakdown study and withstand characteristics of insulating materials. The course also describes the generation and measurement of DC, AC and Impulse voltages as well various testing techniques.

Learning Objectives:

- To understand electric field distribution and computation in different configuration of electrode systems.
- To understand HV breakdown phenomena in gases, liquids and solids dielectric materials.
- To acquaint with the generating principle of operation and design of HVDC, AC and Impulse voltages and impulse currents.
- To understand various techniques of AC, DC and Impulse measurement of high voltages and currents.
- To understand the insulating characteristics of dielectric materials.
- To understand the various testing techniques of HV equipments.

UNIT–I:

Introduction to High Voltage Technology

Electric Field Stresses – Uniform and non–uniform field configuration of electrodes – Estimation and control of electric Stress – Numerical methods for electric field computation.

UNIT–II:

Break down phenomenon in gaseous, liquid and solid insulation

Gases as insulating media – Collision process – Ionization process – Townsend’s criteria of breakdown in gases – Paschen’s law – Liquid as Insulator – Pure and commercial liquids – Breakdown in pure and commercial liquid – Intrinsic breakdown – Electromechanical breakdown – Thermal breakdown –Breakdown of solid dielectrics in practice – Breakdown in composite dielectrics used in practice.

UNIT–III:

Generation of High voltages and High currents

Generation of high DC voltages – Generation of high alternating voltages – Generation of impulse voltages – Generation of impulse currents – Tripping and control of impulse generators.

UNIT–IV:

Measurement of high voltages and High currents

Measurement of high AC, DC and Impulse voltages – Voltages and measurement of high currents – Direct, alternating and Impulse.

UNIT–V:

Non–destructive testing of material and electrical apparatus

Measurement of DC resistivity – Measurement of dielectric constant and loss factor – Partial discharge measurements.

UNIT–VI:

High voltage testing of electrical apparatus

Testing of insulators and bushings – Testing of isolators and circuit breakers – Testing of cables – Testing of transformers – Testing of surge arresters – Radio interference measurements.

Learning Outcomes:

- To be acquainted with the performance of high voltages with regard to different configurations of electrode systems.
- To be able to understand theory of breakdown and withstand phenomena of all types of dielectric materials.
- To acquaint with the techniques of generation of AC,DC and Impulse voltages.
- To be able to apply knowledge for measurement of high voltage and high current AC,DC and Impulse.
- To be in a position to measure dielectric property of material used for HV equipment.
- To know the techniques of testing various equipment's used in HV engineering.

Text Books:

1. High Voltage Engineering by M.S.Naidu and V. Kamaraju – TMH Publications, 3rd Edition.

2. High Voltage Engineering : Fundamentals by E.Kuffel, W.S. Zaengl, J. Kuffel by Elsevier, 2nd Edition.
3. High Voltage Engineering and Technology by Ryan, IET Publishers.

Reference Books:

1. High Voltage Engineering by C.L.Wadhwa, New Age Internationals (P) Limited, 1997.
2. High Voltage Insulation Engineering by Ravindra Arora, Wolfgang Mosch, New.

   Age International (P) Limited, 1995.

SPECIAL ELECTRICAL MACHINES
(Elective – II)

Preamble:

This is an advanced course on electrical machines. Students will be exposed to various special machines which are gaining importance in industry. This course covers topics related to principles, performance and applications of these special machines including switched reluctance motors, stepper motors, permanent magnet dc motors, linear motors and electric motors for traction drives.

Learning Objective:

- To explain theory of operation and control of switched reluctance motor.
- To explain the performance and control of stepper motors, and their applications.
- To describe the operation and characteristics of permanent magnet dc motor.
- To distinguish between brush dc motor and brush less dc motor**.**
- To explain the theory of travelling magnetic field and applications of linear motors.
- To understand the significance of electrical motors for traction drives.

UNIT I:

Switched Reluctance Motor

Principle of operation – Design of stator and rotor pole arc – Power converter for switched reluctance motor – Control of switched reluctance motor.

UNIT II:

Stepper Motors

Construction – Principle of operation – Theory of torque production – Hybrid stepping motor – Variable reluctance stepping motor – Open loop and closed loop control.

UNIT III:

Permanent Magnet DC Motors

Construction – Principle of working – Torque equation and equivalent circuits – Performance characteristics – Moving coil motors.

UNIT IV:

Permanent Magnet Brushless DC Motor

Construction – Principle of operation – Theory of brushless DC motor as variable speed synchronous motor – Sensor less and sensor based control of BLDC motors.

UNIT V:

Linear motors

Linear induction motor: Construction– principle of operation– applications. Linear synchronous motor: Construction – principle of operation– applications.

UNIT VI:

Electric Motors for traction drives

AC motors– DC motors –Single sided linear induction motor for traction drives – Comparison of AC and DC traction.

Learning Outcomes:

The student should be able to

- Explain theory of operation and control of switched reluctance motor.
- Explain the performance and control of stepper motors, and their applications.
- Describe the operation and characteristics of permanent magnet dc motor.
- Distinguish between brush dc motor and brush less dc motor**.**
- Explain the theory of travelling magnetic field and applications of linear motors.
- Understand the significance of electrical motors for traction drives.

Text Books:

1. Special electrical Machines, K.Venkata Ratnam, University press, 2009, New Delhi.
2. Brushless Permanent magnet and reluctance motor drives, Clarenden press, T.J.E. Miller, 1989, Oxford.
3. Special electrical machines, E.G. Janardhanan, PHI learning private limited, 2014.

IV Year – II SEMESTER

T	P	C
3+1	0	3

ELECTIVE – III

ELECTRIC POWER QUALITY

Preamble:

Power quality is a major problem for utilities and customers. Customers using sensitive critical loads need quality power for proper operation of the electrical equipment. It is important for the student to learn the power quality issues and improvement measures provided by the utility companies. This course covers the topics on voltage and current imperfections, harmonics, voltage regulation, power factor improvement, distributed generation, power quality monitoring and measurement equipment.

Learning Objectives:

- To learn different types of power quality phenomena.
- To identify sources for voltage sag, voltage swell, interruptions, transients, long duration over voltages and harmonics in a power system.
- To describe power quality terms and study power quality standards.
- To learn the principle of voltage regulation and power factor improvement methods.
- To explain the relationship between distributed generation and power quality.
- To understand the power quality monitoring concepts and the usage of measuring instruments.

UNIT–I:

Introduction

Overview of power quality – Concern about the power quality – General classes of power quality and voltage quality problems – Transients – Long–duration voltage variations – Short–duration voltage variations – Voltage unbalance – Waveform distortion – Voltage fluctuation – Power frequency variations.

UNIT–II:

Voltage imperfections in power systems

Power quality terms – Voltage sags – Voltage swells and interruptions –

Sources of voltage sag, swell and interruptions – Nonlinear loads – IEEE and IEC standards. Source of transient over voltages – Principles of over voltage protection – Devices for over voltage protection – Utility capacitor switching transients.

UNIT–III

Voltage Regulation and power factor improvement:

Principles of regulating the voltage – Device for voltage regulation – Utility voltage regulator application – Capacitor for voltage regulation – End–user capacitor application – Regulating utility voltage with distributed resources – Flicker – Power factor penalty – Static VAR compensations for power factor improvement.

UNIT– IV

Harmonic distortion and solutions

Voltage distortion vs. Current distortion – Harmonics vs. Transients – Harmonic indices – Sources of harmonics – Effect of harmonic distortion – Impact of capacitors, transformers, motors and meters – Point of common coupling – Passive and active filtering – Numerical problems.

UNIT–V

Distributed Generation and Power Quality

Resurgence of distributed generation – DG technologies – Interface to the utility system – Power quality issues and operating conflicts – DG on low voltage distribution networks.

UNIT–VI

Monitoring and Instrumentation

Power quality monitoring and considerations – Historical perspective of PQ measuring instruments – PQ measurement equipment – Assessment of PQ measuring data – Application of intelligent systems – PQ monitoring standards.

Learning Outcomes:

At the end of this course the student should be able to

- Differentiate between different types of power quality problems.
- Explain the sources of voltage sag, voltage swell, interruptions, transients, long duration over voltages and harmonics in a power system.
- Analyze power quality terms and power quality standards.

- Explain the principle of voltage regulation and power factor improvement methods.
- Demonstrate the relationship between distributed generation and power quality.
- Explain the power quality monitoring concepts and the usage of measuring instruments.

Textbooks:

1. Electrical Power Systems Quality, Dugan R C, McGranaghan M F, Santoso S, and Beaty H W, Second Edition, McGraw–Hill, 2012, 3rd edition.
2. Electric power quality problems –M.H.J. Bollen IEEE series-Wiley india publications, 2011.
3. Power Quality Primer, Kennedy B W, First Edition, McGraw–Hill, 2000.

Reference Books:

1. Understanding Power Quality Problems: Voltage Sags and Interruptions, Bollen M HJ, First Edition, IEEE Press; 2000.
2. Power System Harmonics, Arrillaga J and Watson N R, Second Edition, John Wiley & Sons, 2003.
3. Electric Power Quality control Techniques, W. E. Kazibwe and M. H. Sendaula, Van Nostrad Reinhold, New York.
4. Power Quality c.shankaran, CRC Press, 2001
5. Harmonics and Power Systems –Franciso C.DE LA Rosa–CRC Press (Taylor & Francis).
6. Power Quality in Power systems and Electrical Machines–EwaldF. fuchs, Mohammad A.S. Masoum–Elsevier.

DIGITAL SIGNAL PROCESSING
(Elective – III)

Preamble:

Signals analysis is very important in daily life. Hence it is required to study the different signals (continuous and discrete) and their properties. The behavior of the signals in time and frequency domain are important in analyzing the response of the network. The tools like FFT, DFT, Z–transforms may be used in the analysis of the signals. Filters must be required to eliminate the unwanted signals. Hence digital filter design also required to be studied. Sampling of signals are required to convert continuous to discrete signals. To have knowledge on the implementation signals, DSP processors must be studied.

Learning Objectives:

- To study different types of signals and properties of systems.
- To study the application of Fourier transform to discrete time systems.
- To study the FFT and inverse FFT and its applications to discrete sequences.
- To study the realization of digital filters and their design.
- To study the multi–rate signal processing.
- To study the architecture of digital signal processors.

UNIT–I:

Introduction

Introduction to Digital Signal Processing**:** Discrete time signals & sequences – Linear shift invariant systems – Stability and causality – Linear constant coefficient difference equations.

UNIT–II:

Discrete Fourier Series

Properties of discrete Fourier series, DFS representation of periodic sequences, Discrete Fourier transforms: Properties of DFT, linear convolution of sequences using DFT, Computation of DFT. Relation between Z–transform and DFS.

UNIT–III:

Fast Fourier Transforms

Frequency domain representation of discrete time signals and systems – Fast

Fourier transforms (FFT) – Radix–2 decimation in time and decimation in frequency FFT Algorithms – Inverse FFT – and FFT for composite N.

UNIT–IV:

Realization of Digital Filters

Solution of difference equations of digital filters – Block diagram representation of linear constant – Coefficient difference equations – Basic structures of IIR systems – Transposed forms – Basic structures of FIR systems – System function.

IIR Digital Filters

Analog filter approximations – Butter worth and Chebyshev – Design of IIR Digital filters from analog filters – Design Examples**:** Analog–Digital transformations.

FIR Digital Filters

Characteristics of FIR Digital Filters – Frequency response – Design of FIR Digital Filters using Window Techniques – Frequency Sampling technique – Comparison of IIR & FIR filters.

UNIT–V:

Multirate Digital Signal Processing:

Decimation – Interpolation – Down sampling – Up sampling rate – Conversion – Implementation of sampling rate conversion.

UNIT–VI:

Introduction to Digital Signal Processors(DSP):

Introduction to programmable DSPs**:** Multiplier and Multiplier Accumulator (MAC) – Modified bus structures and memory access schemes in DSPs – Multiple access memory – Multiport memory – VLSI architecture – Pipelining – Special addressing modes – On–chip peripherals – Architecture of TMS 320C5X – Introduction – Bus structure – Central arithmetic logic unit – Auxiliary registrar – Index registrar – Auxiliary register compare register – Block move address register – Parallel logic unit – Memory mapped registers – Program controller – Some flags in the status registers – On–chip registers, On–chip peripherals.

Learning outcomes:

- Able to study different types of signals and properties of systems.
- Able to apply of Fourier transform to discrete time systems.
- Able to apply the FFT and inverse FFT to discrete sequences.

- Able to realize and design digital filters.
- Able to understand the multi–rate signal processing.
- Able to understand architecture of digital signal processors.

Text Books:

1. Digital Signal Processing – Alan V. Oppenheim, Ronald W. Schafer, PHI Ed., 2006
2. Digital Signal Processing, Principles, Algorithms, and Applications: John G. Proakis, Dimitris G. Manolakis, Pearson Education / PHI, 2007

Reference Books:

1. Digital Signal Processing: Andreas Antoniou, TATA McGraw Hill , 2006
2. Digital Signal Processing: MH Hayes, Schaum’s Outlines, TATA Mc–Graw Hill, 2007.
3. DSP Primer – C. Britton Rorabaugh, Tata Mc Graw Hill, 2005.
4. Fundamentals of Digital Signal Processing using Matlab – Robert J. Schilling, Sandra L. Harris, Thomson, 2007.
5. Digital Signal Processors – Architecture, Programming and Applications, B.Venkataramani, M.Bhaskar, TATA McGraw Hill, 2002.

FLEXIBLE ALTERNATING CURRENT TRANSMISSION SYSTEMS (FACTS)
(Elective – III)

Preamble:

Flexible Alternating Current Transmission System controllers have become a part of modern power system. It is important for the student to understand the principle of operation of series and shunt compensators by using power electronics. As the heart of many power electronic controllers is a voltage source converter (VSC), the student should be acquainted with the operation and control of VSC. Two modern power electronic controllers are also introduced.

Learning Objectives:

- To learn the basics of power flow control in transmission lines by using FACTS controllers
- To explain the operation and control of voltage source converter.
- To discuss compensation methods to improve stability and reduce power oscillations in the transmission lines.
- To learn the method of shunt compensation by using static VAR compensators.
- To learn the methods of compensation by using series compensators
- To explain the operation of two modern power electronic controllers (Unified Power Quality Conditioner and Interline Power Flow Controller).

UNIT–I:

Introduction to FACTS

Power flow in an AC System – Loading capability limits – Dynamic stability considerations – Importance of controllable parameters – Basic types of FACTS controllers – Benefits from FACTS controllers – Requirements and characteristics of high power devices – Voltage and current rating – Losses and speed of switching – Parameter trade–off devices.

UNIT–II:

Voltage source and Current source converters

Concept of voltage source converter(VSC) – Single phase bridge converter – Square–wave voltage harmonics for a single–phase bridge converter – Three–phase full wave bridge converte r– Three–phase current source converter – Comparison of current source converter with voltage source converter.

UNIT–III:

Shunt Compensators–1

Objectives of shunt compensation – Mid–point voltage regulation for line segmentation – End of line voltage support to prevent voltage instability – Improvement of transient stability – Power oscillation damping.

Methods of controllable VAR generation

Variable impedance type static VAR generators – Thyristor Controlled Reactor (TCR) and Thyristor Switched Reactor (TSR).

UNIT–IV:

Shunt Compensators–2

Thyristor Switched Capacitor(TSC)– Thyristor Switched Capacitor – Thyristor Switched Reactor (TSC–TCR). Static VAR compensator(SVC) and Static Compensator(STATCOM)**:** The regulation and slope transfer function and dynamic performance – Transient stability enhancement and power oscillation damping– Operating point control and summary of compensation control.

UNIT V:

Series Compensators

Static series compensators**:** Concept of series capacitive compensation – Improvement of transient stability – Power oscillation damping – Functional requirements. GTO thyristor controlled Series Capacitor (GSC) – Thyristor Switched Series Capacitor (TSSC) and Thyristor Controlled Series Capacitor (TCSC).

UNIT–VI:

Combined Controllers

Schematic and basic operating principles of unified power flow controller(UPFC) and Interline power flow controller(IPFC) – Application of these controllers on transmission lines.

Learning Outcomes:

The student should be able to

- Determine power flow control in transmission lines by using FACTS controllers.
- Explain operation and control of voltage source converter.

- Discuss compensation methods to improve stability and reduce power oscillations in the transmission lines.
- Explain the method of shunt compensation by using static VAR compensators.
- Appreciate the methods of compensations by using series compensators.
- Explain the operation of modern power electronic controllers (Unified Power Quality Conditioner and Interline Power Flow Controller).

Text Books:

1. "Understanding FACTS" N.G.Hingorani and L.Guygi, IEEE Press.Indian Edition is available:—Standard Publications, 2001.
2. "Flexible ac transmission system (FACTS)" Edited by Yong Hue Song and Allan T Johns, Institution of Electrical Engineers, London.
3. Thyristor-based FACTS Controllers for Electrical Transmission Systems, by R.Mohan Mathur and Rajiv K.Varma, Wiley.

IV Year – II SEMESTER	T	P	C
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ELECTIVE – IV

OOPS THROUGH JAVA

Preamble:

This course teaches students how to develop Java applications. Topics covered include the Java programming language syntax, OO programming using Java, exception handling, file input/output, threads, collection classes, and networking.

Learning Objectives:

- Focus on object oriented concepts and java program structure and its installation.
- Comprehension of java programming constructs, control structures in Java.
- Implementing Object oriented constructs such as various class hierarchies, interfaces and exception handling.
- Understanding of Thread concepts and I/O in Java.
- Being able to build dynamic user interfaces using applets and Event handling in java.
- Understanding of various components of Java AWT and Swing and writing code snippets using them.

UNIT I:

Introduction to OOP

Introduction, Need of Object Oriented Programming, Principles of Object Oriented Languages, Procedural languages Vs OOP, Applications of OOP, History of JAVA, Java Virtual Machine, Java Features, Program structures, Installation of JDK1.6

UNIT II:

Programming Constructs

Variables, Primitive Datatypes, Identifiers- Naming Coventions, Keywords, Literals, Operators-Binary, Unary and ternary, Expressions, Precedence rules and Associativity, Primitive TypeConversion and Casting, Flow of control-Branching, Conditional, loops.

Classes and Objects- classes, Objects, Creating Objects, Methods, constructors-Constructor overloading, cleaning up unused objects-Garbage collector, Class variable and Methods-Static keyword, this keyword, Arrays, Command line arguments.

UNIT III:

Inheritance: Types of Inheritance, Deriving classes using extends keyword, Method overloading, super keyword, final keyword, Abstract class.

Interfaces, Packages and Enumeration: Interface-Extending interface, Interface Vs Abstract classes, Packages-Creating packages, using Packages, Access protection, java. lang package.

Exceptions & Assertions - Introduction, Exception handling techniques-try... catch, throw, throws, finally block, user defined exception, Exception Encapsulation and Enrichment, Assertions.

UNIT IV:

MultiThreading : java.lang.Thread, The main Thread, Creation of new threads, Thread priority, Multithreading- Using isAlive () and join (), Syncronization, suspending and Resuming threads, Communication between Threads

Input/Output: reading and writing data, java.io package

UNIT V:

Applets- Applet class, Applet structure, An Example Applet Program, Applet Life Cycle, paint (), update () and repaint ()

Event Handling -Introduction, Event Delegation Model, java.awt.event Description, Sources of Events, Event Listeners, Adapter classes, Inner classes.

UNIT VI:

Abstract Window Toolkit

Why AWT?, java.awt package, Components and Containers, Button, Label, Checkbox, Radio buttons, List boxes, Choice boxes, Text field and Text area, container classes, Layouts, Menu, Scroll bar

Swing:

Introduction, JFrame, JApplet, JPanel, Components in swings, Layout Managers, JList and JScroll Pane, Split Pane, JTabbedPane, Dialog Box

Pluggable Look and Feel.

Learning Outcomes:

- Understand the format and use of objects.
- Understand basic input/output methods and their use.
- Understand object inheritance and its use.
- Understand development of JAVA applets vs. JAVA applications.
- Understand the use of various system libraries.

Text Books:

1. The Complete Refernce Java, 8ed, Herbert Schildt, TMH
2. Programming in JAVA, Sachin Malhotra, Saurabh choudhary, Oxford.
3. JAVA for Beginners, 4e, Joyce Farrell, Ankit R. Bhavsar, Cengage Learning.
4. Object oriented programming with JAVA, Essentials and Applications, Raj Kumar Bhuyya, Selvi, Chu TMH.
5. Introduction to Java rogramming, 7th ed, Y Daniel Liang, Pearson.

Reference Books:

1. JAVA Programming, K. Rajkumar. Pearson.
2. Core JAVA, Black Book, Nageswara Rao, Wiley, Dream Tech
3. Core JAVA for Beginners, Rashmi Kanta Das, Vikas.
4. Object Oriented Programming through JAVA , P Radha Krishna, University Press.

UNIX AND SHELL PROGRAMMING
(Elective – IV)

Learning Objectives:

- to provide a comprehensive introduction to Shell Programming.
- have the fundamental skills required to write simple and complex Shell scripts to automate jobs and processes in the Unix environment.

UNIT I:

Introduction to Unix:- Architecture of Unix, Features of Unix, Unix Commands – PATH, man, echo, printf, script, passwd, uname, who, date, stty, pwd, cd, mkdir, rmdir, ls, cp, mv, rm, cat, more, wc, lp, od, tar, gzip.

UNIT II :

Unix Utilities:- Introduction to unix file system, vi editor, file handling utilities, security by file permissions, process utilities, disk utilities, networking commands, unlink, du, df, mount, umount, find, unmask, ulimit, ps, w, finger, arp, ftp, telnet, rlogin.Text processing utilities and backup utilities, detailed commands to be covered are tail, head, sort, nl, uniq, grep, egrep, fgrep, cut, paste, join, tee, pg, comm, cmp, diff, tr, awk, cpio.

UNIT III :

File Management : File Structures, System Calls for File Management – create, open, close, read, write, lseek, link, symlink, unlink, stat, fstat, lstat, chmod, chown, Directory API – opendir, readdir, closedir, mkdir, rmdir, umask.

Introduction to Shells : Unix Session, Standard Streams, Redirection, Pipes, Tee Command, Command Execution, Command- Line Editing, Quotes, Command Substitution, Job Control, Aliases, Variables, Predefined Variables, Options, Shell/Environment Customization.

Filters : Filters and Pipes, Concatenating files, Display Beginning and End of files, Cut and Paste, Sorting, Translating Characters, Files with Duplicate Lines, Count characters, Words or Lines, Comparing Files.

UNIT IV :

Grep : Operation, grep Family, Searching for File Content.

Sed : Scripts, Operation, Addresses, commands, Applications, grep and sed.

awk: Execution, Fields and Records, Scripts, Operations, Patterns, Actions, Associative Arrays, String.

Functions, String Functions, Mathematical Functions, User – Defined Functions, Using System commands, in awk, Applications, awk and grep, sed and awk.

UNIT V :

Interactive Korn Shell : Korn Shell Features, Two Special Files, Variables, Output, Input, Exit Status of a Command, eval Command, Environmental Variables, Options, Startup Scripts, Command History, Command Execution Process.

Korn Shell Programming : Basic Script concepts, Expressions, Decisions: Making Selections, Repetition, special Parameters and Variables, changing Positional Parameters, Argument Validation, Debugging Scripts, Script Examples.

UNIT VI :

Interactive C Shell : C shell features, Two Special Files, Variables, Output, Input, Exit Status of a Command, eval Command, Environmental Variables, On-Off Variables, Startup and Shutdown Scripts, Command History, Command Execution Scripts.

C Shell Programming : Basic Script concepts, Expressions, Decisions: Making Selections, Repetition, special Parameters and Variables, changing Positional Parameters, Argument Validation, Debugging Scripts, Script Examples.

Learning Outcomes:

Upon completing this course students will have skills in:

1. Use UNIX shells and commands to create powerful data processing applications.
2. Build UNIX applications using the shell command interpreter and UNIX commands.
3. Use UNIX at the command line to manage data, files, and programs.
4. Use UNIX editors and tools to create and modify data files and documents.

Text Books :

1. Unix and shell Programming Behrouz A. Forouzan, Richard F. Gilberg. Thomson.

2. Your Unix the ultimate guide, Sumitabha Das, TMH. 2nd Edition. 2007-2008 Page 34 of 95.

References Books:

1. Unix for programmers and users, 3rd edition, Graham Glass, King Ables, Pearson Education.
2. Unix programming environment, Kernighan and Pike, PHI. / Pearson Education.
3. The Complete Reference Unix, Rosen, Host, Klee, Farber, Rosinski, Second Edition, TMH.

AI TECHNIQUES
(Elective IV)

Preamble:

The aim of this course is to study the AI techniques such as neural networks and fuzzy systems. The course focuses on the application of AI techniques to electrical engineering.

Learning Objectives:

- To study various methods of AI
- To study the models and architecture of artificial neural networks.
- To study the ANN paradigms.
- To study the fuzzy sets and operations.
- To study the fuzzy logic systems.
- To study the applications of AI.

UNIT–I:

Introduction to AI techniques

Introduction to artificial intelligence systems– Humans and Computers – Knowledge representation – Learning process – Learning tasks – Methods of AI techniques.

UNIT–II:

Neural Networks

Organization of the Brain – Biological Neuron – Biological and Artificial neuron Models, MC Culloch-pitts neuron model, Activation functions, Learning rules, neural network architectures- Single-layer feed-forward networks: – Perceptron, Learning algorithm for perceptron- limitations of Perceptron model

UNIT–III:

ANN paradigm

Multi-layer feed-forward network (based on Back propagation algorithm)– Radial-basisn function networks- Recurrent networks (Hopfield networks).

UNIT – IV:

Classical and Fuzzy Sets

Introduction to classical sets – properties – Operations and relations – Fuzzy sets – Membership – Uncertainty – Operations – Properties – Fuzzy relations – Cardinalities – Membership functions.

UNIT–V:

Fuzzy Logic System Components

Fuzzification – Membership value assignmen – Development of rule base and decision making system – Defuzzification to crisp sets – Defuzzification methods – Basic hybrid system.

UNIT–VI:

Application of AI techniques

Load forecasting – Load flow studies – Economic load dispatch – Load frequency control – Reactive power control – Speed control of dc and ac motors.

Text Books:

1. Neural Networks, Fuzzy logic, Genetic algorithms: synthesis and applications by S.Rajasekaran and G.A. Vijayalakshmi Pai – PHI Publication.
2. Fuzzy logic with fuzzy applications- by T.J. Ross, TMH.

Reference Books:

1. Introduction to Artificial Neural Systems – Jacek M. Zurada, Jaico Publishing House, 1997.
2. Fundamentals of Neural Networks Architectures, Algorithms and Applications - by laurene Fausett, Pearson.
3. Neural Networks, Algorithms, Applications and programming Techniques by James A. Freeman, David M. Skapura.
4. Introduction to Neural Networks using MATLAB 6.0 by S N Sivanandam, S Sumathi, S N Deepa TMGH

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POWER SYSTEM REFORMS
(Elective IV)

Preamble:

This course introduces the concepts and issues of power system reforms and aims at computation of Available Transfer Capability (ATC), Congestion Management, Electricity Pricing, Ancillary services Management and Power system operation in competitive environment.

Learning Objectives:

- To study fundamentals of power system deregulation and restructuring.
- To study available transfer capability.
- To study congestion management
- To study various electricity pricing.
- To study operation of power system in deregulated environment.
- To study importance of Ancillary services management.

UNIT–I

Over view of key issues in electric utilities

Introduction – Restructuring models – Independent system operator (ISO) – Power Exchange – Market operations – Market Power – Standard cost – Transmission Pricing – Congestion Pricing – Management of Inter zonal/Intra zonal Congestion.

UNIT–II

OASIS: Open Access Same–Time Information System

Structure of OASIS – Processing of Information – Transfer capability on OASIS – Definitions Transfer Capability Issues – ATC – TTC – TRM – CBM calculations – Methodologies to calculate ATC.

UNIT–III

Congestion Management

Introduction to congestion management – Methods to relieve congestion

UNIT–IV

Electricity Pricing:

Introduction – Electricity price volatility electricity price indexes –

Challenges to electricity pricing – Construction of forward price curves – Short–time price forecasting.

UNIT–V

Power system operation in competitive environment:

Introduction – Operational planning activities of ISO – The ISO in pool markets – The ISO in bilateral markets – Operational planning activities of a Genco.

UNIT–VI

Ancillary Services Management:

Introduction – Reactive power as an ancillary service – A review – Synchronous generators as ancillary service providers.

Learning Outcomes:

- Will understand importance of power system deregulation and restructuring.
- Able to compute ATC.
- Will understand transmission congestion management.
- Able to compute electricity pricing in deregulated environment.
- Will be able to understand power system operation in deregulated environment.
- Will understand importance of ancillary services.

Text Books:

1. Kankar Bhattacharya, Math H.J. Boller, Jaap E.Daalder, ‘Operation of Restructured Power System’ Klum,er Academic Publisher – 2001
2. Mohammad Shahidehpour, and Muwaffaq alomoush, – “Restructured electrical Power systems” Marcel Dekker, Inc. 2001
3. Loi Lei Lai; “Power system Restructuring and Deregulation”, Jhon Wiley & Sons Ltd., England.
4. Electrical Power Distribution Case studies from Distribution reform, upgrades and Management (DRUM) Program, by USAID/India, TMH.

SYSTEMS ENGINEERING
(Elective IV)

Preamble:

This course is intended to introduce the student to the systems engineering process used to create multidisciplinary solutions to complex problems which have multiple, often conflicting objectives. The course will provide an overview of systems engineering in the context of large developmental programs. By focusing on the objectives, principles and practices of systems engineering, the course will enable the student to better understand the functions, capabilities and limitations of systems engineering.

Learning Objectives:

- To understand the foundations of systems Engineering.
- To understand the process of engineering systems systematically
- To understand how to deploy (put to use) the systems engineered.
- To understand the supporting systems during systems life cycle.
- To understand the application of systems engineering in product and service space.
- To understand systems engineering in perspective of related disciplines project management and software engineering.

UNIT–I:

Introduction to Systems**:** Systems Fundamentals – Systems Science – Systems Thinking – Modeling Systems.

UNIT –II:

Systems Engineering and Management: System life cycle models – System vision and mission – Stakeholder needs and requirements – System requirements – Logical architecture design – Physical architecture design – System analysis – System realization – System implementation – System integration – System verification – System validation.

UNIT – III:

System deployment and use – System deployment – Operation of the system – System maintenance – Logistics.

UNIT – IV:

Systems engineering management – Planning – Assessment and Control –

Risk Management – Measurement – Decision Management – Configuration Management – Information Management – Quality Management.

UNIT – V:
Applications of systems engineering **–** Product systems engineering **–** Services Systems engineering **–** Enterprise systems engineering

UNIT – VI:
Enabling systems engineering – People**:** Enabling teams and individuals – Software engineering, Project management – Case studies.

Learning Outcomes:

- To be able to appreciate and evaluate systems in general and apply to specific systems.
- Should engineer successful systems fit for intended purpose. Right from concept to development.
- Should be able to successfully deploy the new systems developed.
- Should be able to leverage the support systems for success of systems from womb to tomb.
- Should be able to apply systems engineering in engineering product and services.
- Should be able to relate systems engineering with project management and software engineering.

Text books:

1. SEBOK Guide to the Systems Engineering Body of Knowledge (SEBoK), version 1.2 – INCOSEwww.sebowiki.org/wiki/incose systems engineering Hand Book.

Reference Books:

1. Systems engineering principles and practice second edition John wiley Alexander Kossiakoff etal.
2. Systems engineering with Economics, Probability and Statistics Khisty C.Jotin. 2nd edition, 2nd edition J Ross publications.

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